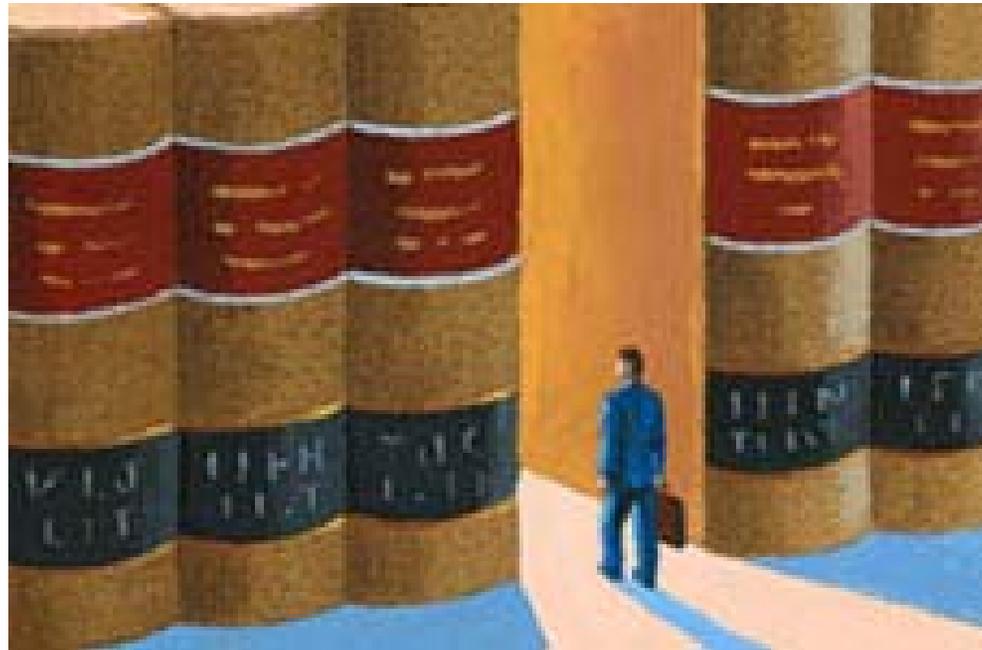




F. Description Logics – Part 2



This section is based on material from:

- Carsten Lutz, Uli Sattler: <http://www.computational-logic.org/content/events/iccl-ss-2005/lectures/lutz/index.php?id=24>
- Ian Horrocks: <http://www.cs.man.ac.uk/~horrocks/Teaching/cs646/>

Syntax für DLs (ohne concrete domains)

Concepts		
ALC	Atomic	A, B
	Not	$\neg C$
	And	$C \sqcap D$
	Or	$C \sqcup D$
	Exists	$\exists R.C$
	For all	$\forall R.C$
Q(N)	At least	$\geq n R.C$ ($\geq n R$)
	At most	$\leq n R.C$ ($\leq n R$)
O	Nominal	$\{i_1, \dots, i_n\}$

Roles		
—	Atomic	R
	Inverse	R^-

Ontology (=Knowledge Base)

Concept Axioms (TBox)	
Subclass	$C \sqsubseteq D$
Equivalent	$C \equiv D$

Role Axioms (RBox)	
\sqsubseteq Subrole	$R \sqsubseteq S$
\mathcal{S} Transitivity	$\text{Trans}(S)$

Assertional Axioms (ABox)	
Instance	$C(a)$
Role	$R(a, b)$
Same	$a = b$
Different	$a \neq b$

S = ALC + Transitivity

OWL DL = SHOIN(D) (D: concrete domain)

The Description Logic \mathcal{ALC} : Syntax

Atomic types: concept names A, B, \dots (unary predicates)
role names R, S, \dots (binary predicates)

Constructors:

- $\neg C$ (negation)
- $C \sqcap D$ (conjunction)
- $C \sqcup D$ (disjunction)
- $\exists R.C$ (existential restriction)
- $\forall R.C$ (value restriction)

Abbreviations:

- $C \rightarrow D = \neg C \sqcup D$ (implication)
- $C \leftrightarrow D = C \rightarrow D \sqcap D \rightarrow C$ (bi-implication)
- $\top = (A \sqcup \neg A)$ (top concept)
- $\perp = A \sqcap \neg A$ (bottom concept)



Examples

- $\text{Person} \sqcap \text{Female}$
- $\text{Person} \sqcap \exists \text{attends. Course}$
- $\text{Person} \sqcap \forall \text{attends. (Course} \rightarrow \neg \text{Easy)}$
- $\text{Person} \sqcap \exists \text{teaches. (Course} \sqcap \forall \text{attended-by. (Bored} \sqcup \text{Sleeping))}$



Interpretations

Semantics based on **interpretations** $(\Delta^{\mathcal{I}}, \cdot^{\mathcal{I}})$, where

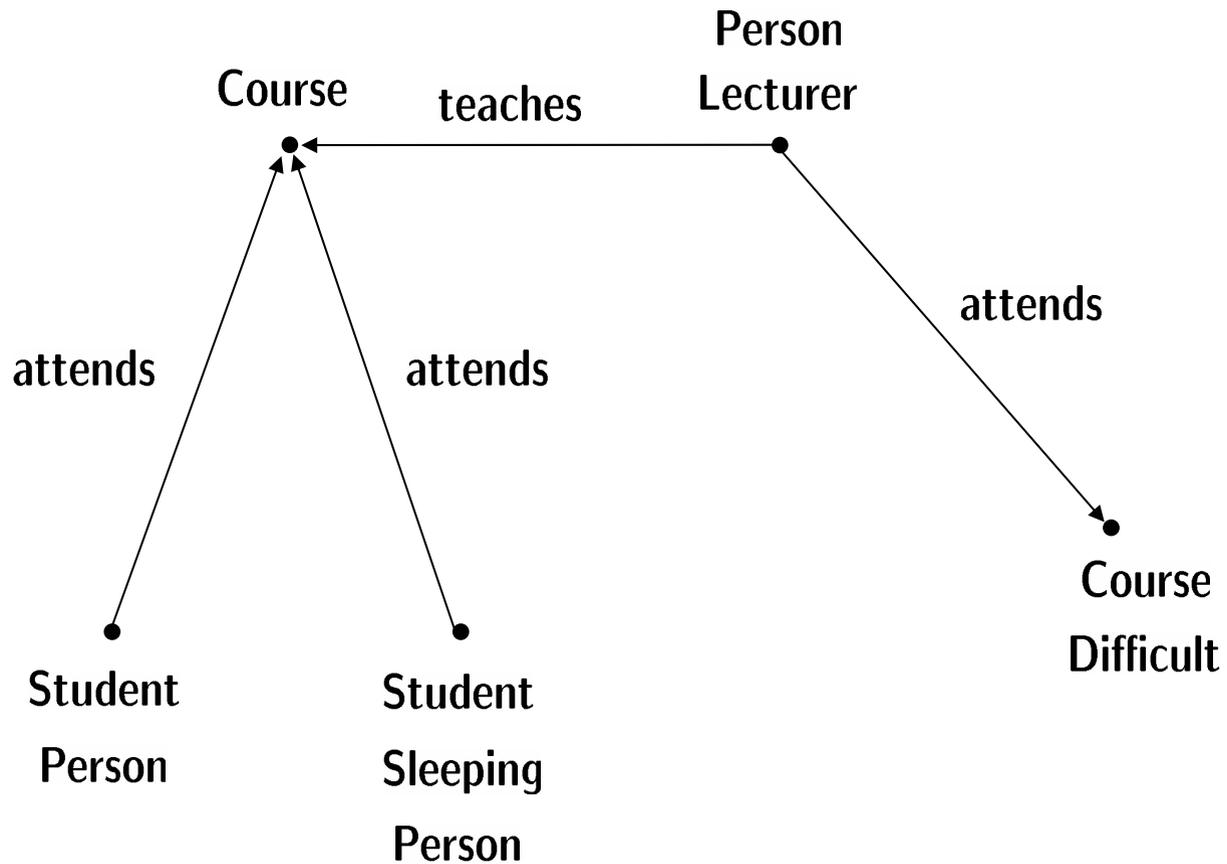
- $\Delta^{\mathcal{I}}$ is a non-empty set (the **domain**)
- $\cdot^{\mathcal{I}}$ is the **interpretation function** mapping
 - each concept name A to a subset $A^{\mathcal{I}}$ of $\Delta^{\mathcal{I}}$ and
 - each role name R to a binary relation $R^{\mathcal{I}}$ over $\Delta^{\mathcal{I}}$.

Intuition: interpretation is **complete** description of the world

Technically: interpretation is first-order structure
with only unary and binary predicates



Example

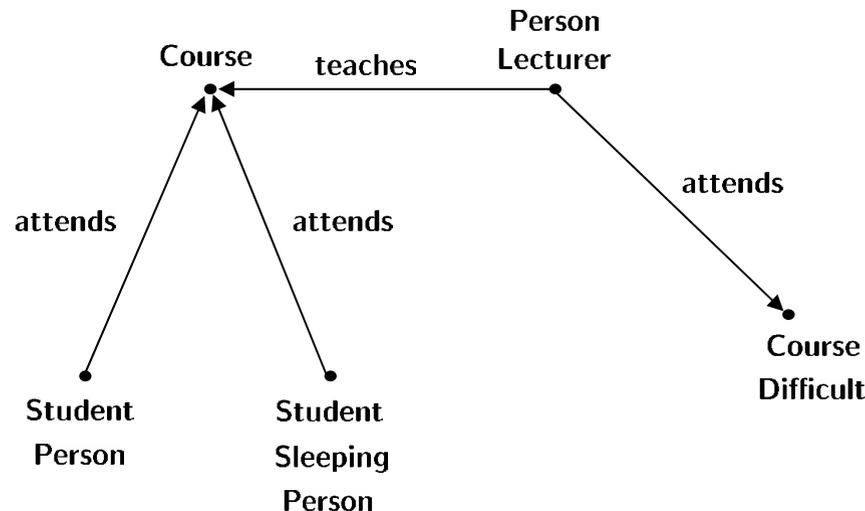


Semantics of Complex Concepts

$$(\neg C)^{\mathcal{I}} = \Delta^{\mathcal{I}} \setminus C^{\mathcal{I}} \quad (C \sqcap D)^{\mathcal{I}} = C^{\mathcal{I}} \cap D^{\mathcal{I}} \quad (C \sqcup D)^{\mathcal{I}} = C^{\mathcal{I}} \cup D^{\mathcal{I}}$$

$$(\exists R.C)^{\mathcal{I}} = \{d \mid \text{there is an } e \in \Delta^{\mathcal{I}} \text{ with } (d, e) \in R^{\mathcal{I}} \text{ and } e \in C^{\mathcal{I}}\}$$

$$(\forall R.C)^{\mathcal{I}} = \{d \mid \text{for all } e \in \Delta^{\mathcal{I}}, (d, e) \in R^{\mathcal{I}} \text{ implies } e \in C^{\mathcal{I}}\}$$



Person \sqcap \exists attends.Course

Person \sqcap \forall attends. $(\neg$ Course \sqcup Difficult)



TBoxes

Capture an application's terminology means **defining** concepts

TBoxes are used to store concept definitions:

Syntax:

finite set of concept equations $A \doteq C$

with A **concept name** and C concept

left-hand sides must be **unique!**

Semantics:

interpretation \mathcal{I} **satisfies** $A \doteq C$ iff $A^{\mathcal{I}} = C^{\mathcal{I}}$

\mathcal{I} is **model** of \mathcal{T} if it satisfies all definitions in \mathcal{T}

E.g.: Lecturer \doteq Person $\sqcap \exists \text{teaches.Course}$

Yields two kinds of concept names: **defined** and **primitive**



TBoxes are used as ontologies:

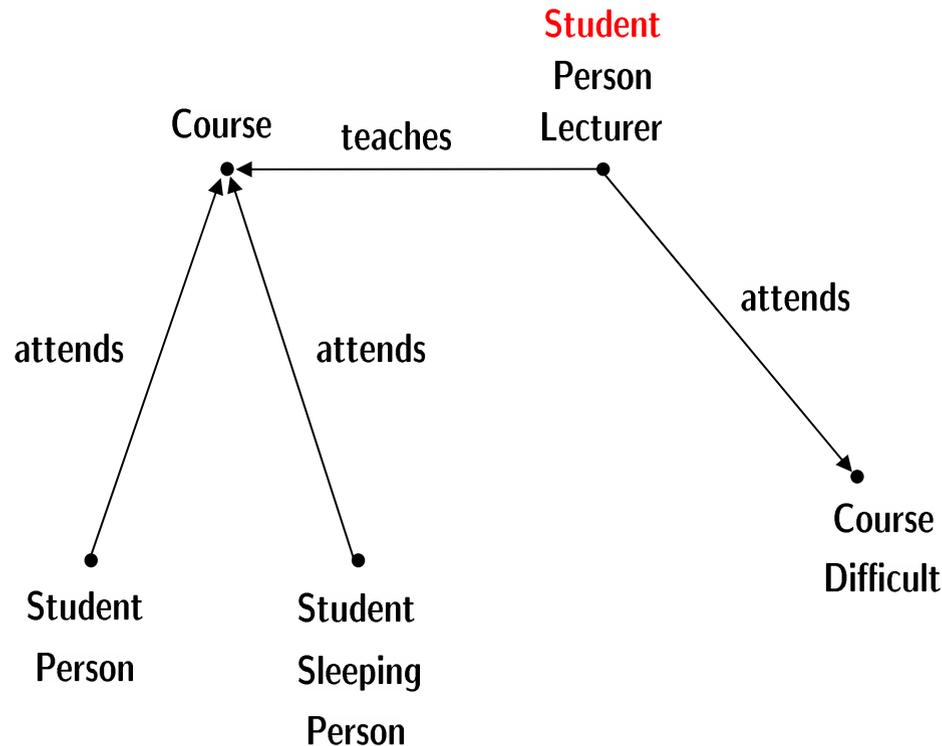
$$\text{Woman} \doteq \text{Person} \sqcap \text{Female}$$
$$\text{Man} \doteq \text{Person} \sqcap \neg \text{Woman}$$
$$\text{Lecturer} \doteq \text{Person} \sqcap \exists \text{teaches.Course}$$
$$\text{Student} \doteq \text{Person} \sqcap \exists \text{attends.Course}$$
$$\text{BadLecturer} \doteq \text{Person} \sqcap \forall \text{teaches.}(\text{Course} \rightarrow \text{Boring})$$

TBox: Example II

A TBox restricts the set of **admissible** interpretations.

$\text{Lecturer} \doteq \text{Person} \sqcap \exists \text{teaches.Course}$

$\text{Student} \doteq \text{Person} \sqcap \exists \text{attends.Course}$



C subsumed by D w.r.t. \mathcal{T} (written $C \sqsubseteq_{\mathcal{T}} D$)

iff

$C^{\mathcal{I}} \subseteq D^{\mathcal{I}}$ holds for all models \mathcal{I} of \mathcal{T}

Intuition: If $C \sqsubseteq_{\mathcal{T}} D$, then D is **more general** than C

Example:

Lecturer \doteq Person \sqcap \exists teaches.Course

Student \doteq Person \sqcap \exists attends.Course

Then

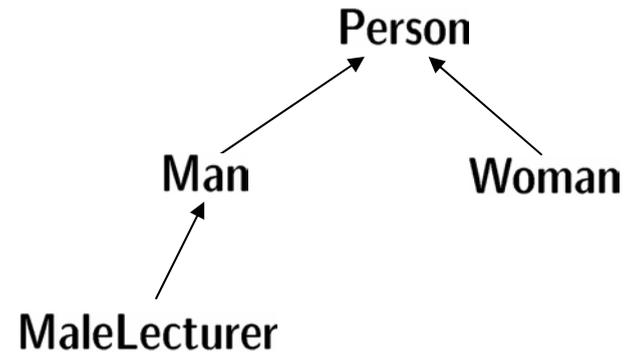
Lecturer \sqcap \exists attends.Course $\sqsubseteq_{\mathcal{T}}$ Student

Classification: arrange all defined concepts from a TBox in a hierarchy w.r.t. generality

$\text{Woman} \doteq \text{Person} \sqcap \text{Female}$

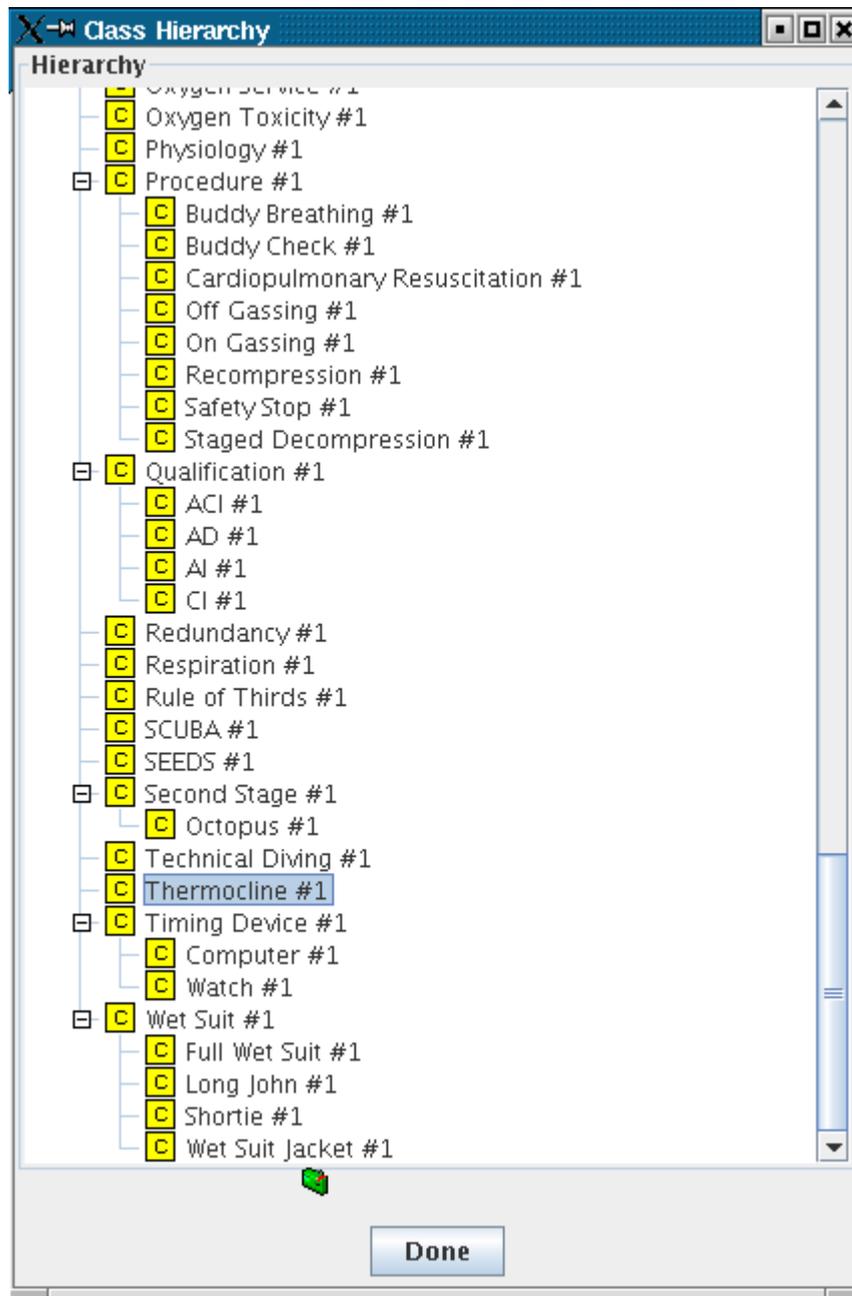
$\text{Man} \doteq \text{Person} \sqcap \neg \text{Woman}$

$\text{MaleLecturer} \doteq \text{Man} \sqcap \exists \text{teaches.Course}$



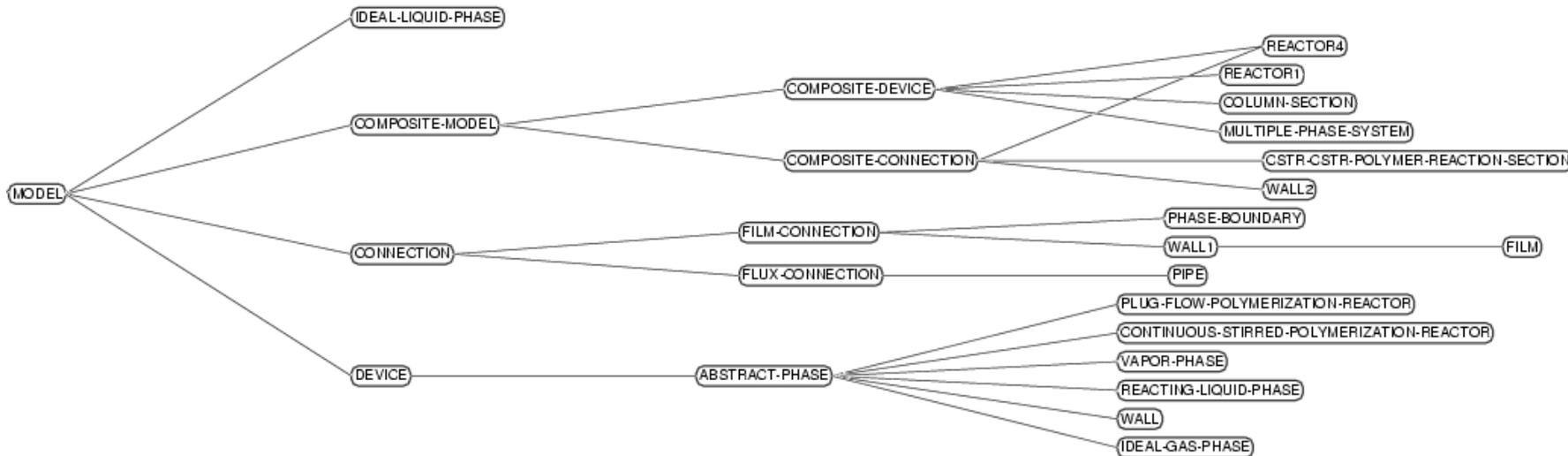
Can be computed using multiple subsumption tests

Provides a principled view on ontology for browsing, maintaining, etc.



A Concept Hierarchy

Excerpt from a process engineering ontology



C is **satisfiable** w.r.t. \mathcal{T} iff \mathcal{T} has a model with $C^{\mathcal{I}} \neq \emptyset$

Intuition: If unsatisfiable, the concept contains a contradiction.

Example: $\text{Woman} \doteq \text{Person} \sqcap \text{Female}$

$\text{Man} \doteq \text{Person} \sqcap \neg \text{Woman}$

Then $\exists \text{sibling}.\text{Man} \sqcap \forall \text{sibling}.\text{Woman}$ is unsatisfiable w.r.t. \mathcal{T}

Subsumption can be reduced to (un)satisfiability and vice versa:

- $C \sqsubseteq_{\mathcal{T}} D$ iff $C \sqcap \neg D$ is not satisfiable w.r.t. \mathcal{T}
- C is satisfiable w.r.t. \mathcal{T} if not $C \sqsubseteq_{\mathcal{T}} \perp$.

Many reasoners decide satisfiability rather than subsumption.

Definitorial TBoxes

A **primitive interpretation** for TBox \mathcal{T} interpretes

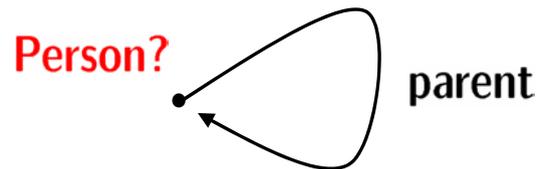
- the **primitive** concept names in \mathcal{T}
- all role names

A TBox is called **definitorial** if every primitive interpretation for \mathcal{T}
can be **uniquely** extended to a model of \mathcal{T} .

i.e.: primitive concepts (and roles) uniquely determine defined concepts

Not all TBoxes are definitorial:

$\text{Person} \doteq \exists \text{parent. Person}$



Non-definitorial TBoxes describe **constraints**, e.g. from **background knowledge**

Acyclic TBoxes

TBox \mathcal{T} is **acyclic** if there are no definitorial cycles:

~~Lecturer \doteq Person \sqcap \exists teaches.Course~~

~~Course \doteq \exists has-title.Title \sqcap \exists tought-by.Lecturer~~

Expansion of acyclic TBox \mathcal{T} :

exhaustively replace defined concept names with their definition
(terminates due to acyclicity)

Acyclic TBoxes are **always** definitorial:

first expand, then set $A^{\mathcal{I}} := C^{\mathcal{I}}$ for all $A \doteq C \in \mathcal{T}$



For reasoning, acyclic TBox can be eliminated:

- to decide $C \sqsubseteq_{\mathcal{T}} D$ with \mathcal{T} acyclic,
 - expand \mathcal{T}
 - replace defined concept names in C, D with their definition
 - decide $C \sqsubseteq D$
- analogously for satisfiability

May yield an **exponential blow-up**:

$$A_0 \doteq \forall r.A_1 \sqcap \forall s.A_1$$

$$A_1 \doteq \forall r.A_2 \sqcap \forall s.A_2$$

...

$$A_{n-1} \doteq \forall r.A_n \sqcap \forall s.A_n$$

General Concept Inclusions

View of TBox as set of constraints

General TBox: finite set of general concept implications (GCIs)

$$C \sqsubseteq D$$

with both C and D allowed to be complex

e.g. $\text{Course} \sqcap \forall \text{attended-by.Sleeping} \sqsubseteq \text{Boring}$

Interpretation \mathcal{I} is model of general TBox \mathcal{T} if

$$C^{\mathcal{I}} \subseteq D^{\mathcal{I}} \text{ for all } C \sqsubseteq D \in \mathcal{T}.$$

$C \doteq D$ is abbreviation for $C \sqsubseteq D, D \sqsubseteq C$

e.g. $\text{Student} \sqcap \exists \text{has-favourite.SoccerTeam} \doteq \text{Student} \sqcap \exists \text{has-favourite.Beer}$

Note: $C \sqsubseteq D$ equivalent to $\top \doteq C \rightarrow D$



ABoxes describe a snapshot of the world

An **ABox** is a finite set of **assertions**

$a : C$ (a individual name, C concept)

$(a, b) : R$ (a, b individual names, R role name)

E.g. {peter : Student, (dl-course, uli) : taught-by}

Interpretations \mathcal{I} map each individual name a to an element of $\Delta^{\mathcal{I}}$.

\mathcal{I} **satisfies** an assertion

$a : C$ iff $a^{\mathcal{I}} \in C^{\mathcal{I}}$

$(a, b) : R$ iff $(a^{\mathcal{I}}, b^{\mathcal{I}}) \in R^{\mathcal{I}}$

\mathcal{I} is a **model** for an ABox \mathcal{A} if \mathcal{I} satisfies all assertions in \mathcal{A} .

Note:

- interpretations describe the state of the world in a **complete** way
- ABoxes describe the state of the world in an **incomplete** way

$(\text{uli}, \text{dl-course}) : \text{tought-by} \quad \text{uli} : \text{Female}$

does **not** imply

$\text{dl-course} : \forall \text{tought-by.Female}$

An ABox has **many models!**

An ABox constraints the set of admissible models similar to a TBox

ABox consistency

Given an ABox \mathcal{A} and a TBox \mathcal{T} , do they have a common model?

Instance checking

Given an ABox \mathcal{A} , a TBox \mathcal{T} , an individual name a , and a concept C does $a^{\mathcal{I}} \in C^{\mathcal{I}}$ hold in all models of \mathcal{A} and \mathcal{T} ?

(written $\mathcal{A}, \mathcal{T} \models a : C$)

The two tasks are interreducible:

- \mathcal{A} consistent w.r.t. \mathcal{T} iff $\mathcal{A}, \mathcal{T} \not\models a : \perp$
- $\mathcal{A}, \mathcal{T} \models a : C$ iff $\mathcal{A} \cup \{a : \neg C\}$ is not consistent

Example for ABox Reasoning

ABox

dumbo : Mammal

t14 : Trunk

~~g23 : Darkgrey~~

(dumbo, t14) : bodypart

(dumbo, g23) : color

dumbo : $\forall \text{color}.\text{Lightgrey}$

TBox

Elephant \doteq Mammal \sqcap $\exists \text{bodypart}.\text{Trunk}$ \sqcap $\forall \text{color}.\text{Grey}$

Grey \doteq Lightgrey \sqcup Darkgrey

\perp \doteq Lightgrey \sqcap Darkgrey

1. ABox is inconsistent w.r.t. TBox.
2. dumbo is an instance of Elephant

2. Tableau algorithms for \mathcal{ALC} and extensions

We see a tableau algorithm for \mathcal{ALC} and extend it with

- ① general TBoxes and
- ② inverse roles

Goal: Design sound and complete decision procedures for satisfiability (and subsumption) of DLs which are well-suited for implementation purposes

A tableau algorithm for the satisfiability of \mathcal{ALC} concepts

Goal: design an algorithm which takes an \mathcal{ALC} concept C_0 and

1. returns “*satisfiable*” iff C_0 is satisfiable and
2. terminates, on every input,

i.e., which **decides** satisfiability of \mathcal{ALC} concepts.

Recall: such an algorithm **cannot** exist for FOL since satisfiability of FOL is undecidable.

Idea: our algorithm

- is tableau-based and
- tries to construct a **model** of C_0
- by breaking C_0 down syntactically, thus
- inferring new constraints on such a model.

Preliminaries: Negation Normal Form

To make our life easier, we transform each concept C_0 into an equivalent C_1 in NNF

Equivalent: $C_0 \sqsubseteq C_1$ and $C_1 \sqsubseteq C_0$

NNF: negation occurs only in front of concept names

How? By pushing negation inwards (de Morgan et. al):

$$\neg(C \sqcap D) \rightsquigarrow \neg C \sqcup \neg D$$

$$\neg(C \sqcup D) \rightsquigarrow \neg C \sqcap \neg D$$

$$\neg\neg C \rightsquigarrow C$$

$$\neg\forall R.C \rightsquigarrow \exists R.\neg C$$

$$\neg\exists R.C \rightsquigarrow \forall R.\neg C$$

From now on: concepts are in NNF and

$\text{sub}(C)$ denotes the set of all sub-concepts of C

More intuition

Find out whether $A \sqcap \exists R.B \sqcap \forall R.\neg B$ is satisfiable...
 $A \sqcap \exists R.B \sqcap \forall R.(\neg B \sqcup \exists S.E)$

Our tableau algorithm works on a **completion tree** which

- represents a model \mathcal{I} : **nodes** represent elements of $\Delta^{\mathcal{I}}$
 - \rightsquigarrow each node x is labelled with concepts $\mathcal{L}(x) \subseteq \text{sub}(C_0)$
 $C \in \mathcal{L}(x)$ is read as “ x should be an instance of C ”
 - edges** represent role successorship
 - \rightsquigarrow each edge $\langle x, y \rangle$ is labelled with a role-name from C_0
 $R \in \mathcal{L}(\langle x, y \rangle)$ is read as “ (x, y) should be in $R^{\mathcal{I}}$ ”
- is initialised with a single root node x_0 with $\mathcal{L}(x_0) = \{C_0\}$
- is expanded using **completion rules**

Completion rules for \mathcal{ALC}

\sqcap -rule: if $C_1 \sqcap C_2 \in \mathcal{L}(x)$ and $\{C_1, C_2\} \not\subseteq \mathcal{L}(x)$

then set $\mathcal{L}(x) = \mathcal{L}(x) \cup \{C_1, C_2\}$

\sqcup -rule: if $C_1 \sqcup C_2 \in \mathcal{L}(x)$ and $\{C_1, C_2\} \cap \mathcal{L}(x) = \emptyset$

then set $\mathcal{L}(x) = \mathcal{L}(x) \cup \{C\}$ for some $C \in \{C_1, C_2\}$

\exists -rule: if $\exists S.C \in \mathcal{L}(x)$ and x has no S -successor y with $C \in \mathcal{L}(y)$,

then create a new node y with $\mathcal{L}(\langle x, y \rangle) = \{S\}$ and $\mathcal{L}(y) = \{C\}$

\forall -rule: if $\forall S.C \in \mathcal{L}(x)$ and there is an S -successor y of x with $C \notin \mathcal{L}(y)$

then set $\mathcal{L}(y) = \mathcal{L}(y) \cup \{C\}$

Properties of the completion rules for \mathcal{ALC}

We only apply rules if their application does “something new”

\sqcap -rule: if $C_1 \sqcap C_2 \in \mathcal{L}(x)$ and $\{C_1, C_2\} \not\subseteq \mathcal{L}(x)$

then set $\mathcal{L}(x) = \mathcal{L}(x) \cup \{C_1, C_2\}$

\sqcup -rule: if $C_1 \sqcup C_2 \in \mathcal{L}(x)$ and $\{C_1, C_2\} \cap \mathcal{L}(x) = \emptyset$

then set $\mathcal{L}(x) = \mathcal{L}(x) \cup \{C\}$ for some $C \in \{C_1, C_2\}$

\exists -rule: if $\exists S.C \in \mathcal{L}(x)$ and x has no S -successor y with $C \in \mathcal{L}(y)$,

then create a new node y with $\mathcal{L}(\langle x, y \rangle) = \{S\}$ and $\mathcal{L}(y) = \{C\}$

\forall -rule: if $\forall S.C \in \mathcal{L}(x)$ and there is an S -successor y of x with $C \notin \mathcal{L}(y)$

then set $\mathcal{L}(y) = \mathcal{L}(y) \cup \{C\}$

The \sqcup -rule is non-deterministic:

\sqcap -rule: if $C_1 \sqcap C_2 \in \mathcal{L}(x)$ and $\{C_1, C_2\} \not\subseteq \mathcal{L}(x)$

then set $\mathcal{L}(x) = \mathcal{L}(x) \cup \{C_1, C_2\}$

\sqcup -rule: if $C_1 \sqcup C_2 \in \mathcal{L}(x)$ and $\{C_1, C_2\} \cap \mathcal{L}(x) = \emptyset$

then set $\mathcal{L}(x) = \mathcal{L}(x) \cup \{C\}$ for some $C \in \{C_1, C_2\}$

\exists -rule: if $\exists S.C \in \mathcal{L}(x)$ and x has no S -successor y with $C \in \mathcal{L}(y)$,

then create a new node y with $\mathcal{L}(\langle x, y \rangle) = \{S\}$ and $\mathcal{L}(y) = \{C\}$

\forall -rule: if $\forall S.C \in \mathcal{L}(x)$ and there is an S -successor y of x with $C \notin \mathcal{L}(y)$

then set $\mathcal{L}(y) = \mathcal{L}(y) \cup \{C\}$

Last details on tableau algorithm for \mathcal{ALC}

Clash: a c-tree contains a **clash** if it has a node x with $\perp \in \mathcal{L}(x)$ or $\{A, \neg A\} \subseteq \mathcal{L}(x)$ — otherwise, it is **clash-free**

Complete: a c-tree is **complete** if none of the completion rules can be applied to it

Answer behaviour: when started for C_0 (in NNF!), the tableau algorithm

- is **initialised** with a single root node x_0 with $\mathcal{L}(x_0) = \{C_0\}$
- repeatedly applies the **completion rules** (in whatever order it likes)
- **answer** “ C_0 is satisfiable” iff the completion rules can be applied in such a way that it results in a complete and clash-free c-tree (careful: this is non-deterministic)

...go back to examples

Properties of our tableau algorithm

Lemma: Let C_0 an \mathcal{ALC} -concept in NNF. Then

1. the algorithm terminates when applied to C_0 and
2. the rules can be applied such that they generate a clash-free and complete completion tree iff C_0 is satisfiable.

- Corollary:**
1. Our tableau algorithm decides satisfiability and subsumption of \mathcal{ALC} .
 2. Satisfiability (and subsumption) in \mathcal{ALC} is decidable in PSpace.
 3. \mathcal{ALC} has the finite model property
i.e., every satisfiable concept has a finite model.
 4. \mathcal{ALC} has the tree model property
i.e., every satisfiable concept has a tree model.
 5. \mathcal{ALC} has the finite tree model property
i.e., every satisfiable concept has a finite tree model.

(1) **Termination** is an immediate consequence of these observations:

1. the c-tree is constructed in a **monotonic way**,
each rule either adds nodes or extends node labels, nothing is removed
2. node labels are restricted to subsets of $\text{sub}(C_0)$ and $\# \text{sub}(C_0) \leq |C_0|$,
at each position in C_0 , at most one sub-concepts starts
3. the c-tree is of **bounded breadth** $\leq |C_0|$,
at most 1 successor for each $\exists R.C \in \text{sub}(C_0)$
4. the c-tree is of **bounded depth** $\leq |C_0|$,
the maximal depth of concepts in node labels decreases from a node to its successor,
i.e., for y a successor of x : $\max\{|C| \mid C \in \mathcal{L}(y)\} < \max\{|C| \mid C \in \mathcal{L}(x)\}$

Proof of the Lemma: Soundness

(2) Let the algorithm stop with a complete and clash-free c-tree.

From this, define an interpretation \mathcal{I} as follows:

$$\Delta^{\mathcal{I}} := \{x \mid x \text{ is a node in c-tree}\}$$

$$A^{\mathcal{I}} := \{x \mid A \in \mathcal{L}(x)\} \text{ for concept names } A$$

$$R^{\mathcal{I}} := \{(x, y) \mid y \text{ is an } R\text{-successor of } x \text{ in c-tree}\}$$

and show, by induction on structure of concepts, for all $x \in \Delta^{\mathcal{I}}$, $D \in \text{sub}(C_0, \mathcal{I})$:

$$D \in \mathcal{L}(x) \text{ implies } x \in D^{\mathcal{I}}$$

→ concept names D : by definition of \mathcal{I}

→ for negated concept names D : due to clash-freeness and induction

→ for conjunctions/disjunctions/existential restrictions/universal restrictions D :
due to completeness and by induction

↪ since C_0 is in label of root node, \mathcal{I} is a model of C_0

Proof of the Lemma: Completeness

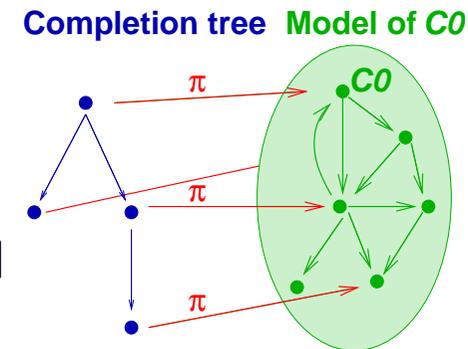
(3) Let C_0 be satisfiable, and let \mathcal{I} be a model of it with $a_0 \in C_0^{\mathcal{I}}$.

Use \mathcal{I} to steer the application of the (only non-deterministic) \sqcup -rule:

Inductively define a total mapping π :

start with $\pi(x_0) = a_0$, and show that

each rule can be applied such that $(*)$ is preserved



$(*)$ if $C \in \mathcal{L}(x)$, then $\pi(x) \in C^{\mathcal{I}}$
 if y is an R -succ. of x , then $\langle \pi(x), \pi(y) \rangle \in R^{\mathcal{I}}$

- easy for \Box - and \forall -rule,
 - for \exists -rule, we need to extend π to the newly created R -successor
 - for \sqcup -rule, if $C_1 \sqcup C_2 \in \mathcal{L}(x)$, $(*)$ implies that $\pi(x) \in (C_1 \sqcup C_2)^{\mathcal{I}}$
 \rightsquigarrow we can choose C_i with $\pi(x) \in C_i^{\mathcal{I}}$ to add to $\mathcal{L}(x)$ and thus preserve $(*)$
- \rightsquigarrow easy to see: $(*)$ implies that c-tree is **clash-free**

Proof of the Lemma: Harvest

Look again at the model \mathcal{I} constructed for a clash-free, complete c-tree:

- \mathcal{I} is
- **finite** because c-tree has finitely many nodes
 - **a tree** because c-tree is a tree

Hence we get Corollary (3) – (5) for free from our proof:

C_0 is satisfiable

- \rightsquigarrow tableau algorithm stops with clash-free, complete c-tree
- $\rightsquigarrow C_0$ has a finite tree model.

Extend tableau algorithm to \mathcal{ALC} with general TBoxes

- Recall:**
- **Concept inclusion:** of the form $C \dot{\sqsubseteq} D$ for C, D (complex) concepts
 - **(General) TBox:** a finite set of concept inclusions
 - \mathcal{I} satisfies $C \dot{\sqsubseteq} D$ iff $C^{\mathcal{I}} \subseteq D^{\mathcal{I}}$
 - \mathcal{I} is a model of TBox \mathcal{T} iff \mathcal{I} satisfies each concept equation in \mathcal{T}
 - C_0 is satisfiable w.r.t. \mathcal{T} iff there is a model \mathcal{I} of \mathcal{T} with $C_0^{\mathcal{I}} \neq \emptyset$

- Goal – Lemma:** Let C_0 an \mathcal{ALC} -concept and \mathcal{T} be a an \mathcal{ALC} -TBox. Then
1. the algorithm terminates when applied to \mathcal{T} and C_0 and
 2. the rules can be applied such that they generate a clash-free and complete completion tree iff C_0 is satisfiable w.r.t. \mathcal{T} .

We extend our tableau algorithm by adding a **new completion rule**:

- remember that nodes represent elements of $\Delta^{\mathcal{I}}$ and
- if $C \sqsubseteq D \in \mathcal{T}$, then for each element x in a model \mathcal{I} of \mathcal{T}
 - if $x \in C^{\mathcal{I}}$, then $x \in D^{\mathcal{I}}$
 - hence $x \in (\neg C)^{\mathcal{I}}$ or $x \in D^{\mathcal{I}}$
 - $x \in (\neg C \sqcup D)^{\mathcal{I}}$
 - $x \in (\mathbf{NNF}(\neg C \sqcup D))^{\mathcal{I}}$

for $\mathbf{NNF}(E)$ the negation normal form of E

Completion rules for \mathcal{ALC} with TBoxes

\sqcap -rule: if $C_1 \sqcap C_2 \in \mathcal{L}(x)$ and $\{C_1, C_2\} \not\subseteq \mathcal{L}(x)$

then set $\mathcal{L}(x) = \mathcal{L}(x) \cup \{C_1, C_2\}$

\sqcup -rule: if $C_1 \sqcup C_2 \in \mathcal{L}(x)$ and $\{C_1, C_2\} \cap \mathcal{L}(x) = \emptyset$

then set $\mathcal{L}(x) = \mathcal{L}(x) \cup \{C\}$ for some $C \in \{C_1, C_2\}$

\exists -rule: if $\exists S.C \in \mathcal{L}(x)$ and x has no S -successor y with $C \in \mathcal{L}(y)$,

then create a new node y with $\mathcal{L}(\langle x, y \rangle) = \{S\}$ and $\mathcal{L}(y) = \{C\}$

\forall -rule: if $\forall S.C \in \mathcal{L}(x)$ and there is an S -successor y of x with $C \notin \mathcal{L}(y)$

then set $\mathcal{L}(y) = \mathcal{L}(y) \cup \{C\}$

\mathcal{T} -rule: if $C_1 \dot{\sqsubseteq} C_2 \in \mathcal{T}$ and $\mathbf{NNF}(\neg C_1 \sqcup C_2) \notin \mathcal{L}(x)$

then set $\mathcal{L}(x) = \mathcal{L}(x) \cup \{\mathbf{NNF}(\neg C_1 \sqcup C_2)\}$

A tableau algorithm for \mathcal{ALC} with general TBoxes

Example: Consider satisfiability of C w.r.t. $\{C \sqsubseteq \exists R.C\}$

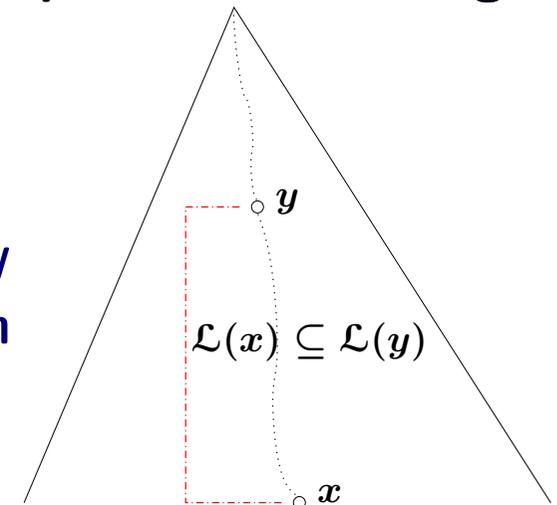
Tableau algorithm no longer terminates!

Reason: size of concepts no longer decreases along paths in a completion tree

Observation: most nodes on this path look the same and we keep repeating ourselves

Regain termination with a “cycle-detection” technique called blocking

Intuitively, whenever we find a situation where y has to satisfy *stronger* constraints than x , we *freeze* x , i.e., block rules from being applied to x



A tableau algorithm for \mathcal{ALC} with general TBoxes: Blocking

- x is **directly blocked** if it has an ancestor y with $\mathcal{L}(x) \subseteq \mathcal{L}(y)$
 - in this case and if y is the “closest” such node to x , we say that x is **blocked by y**
 - a node is **blocked** if it is directly blocked or one of its ancestors is blocked
- ⊕ restrict the application of all rules to nodes which are not blocked

↪ **completion rules for \mathcal{ALC} w.r.t. TBoxes**

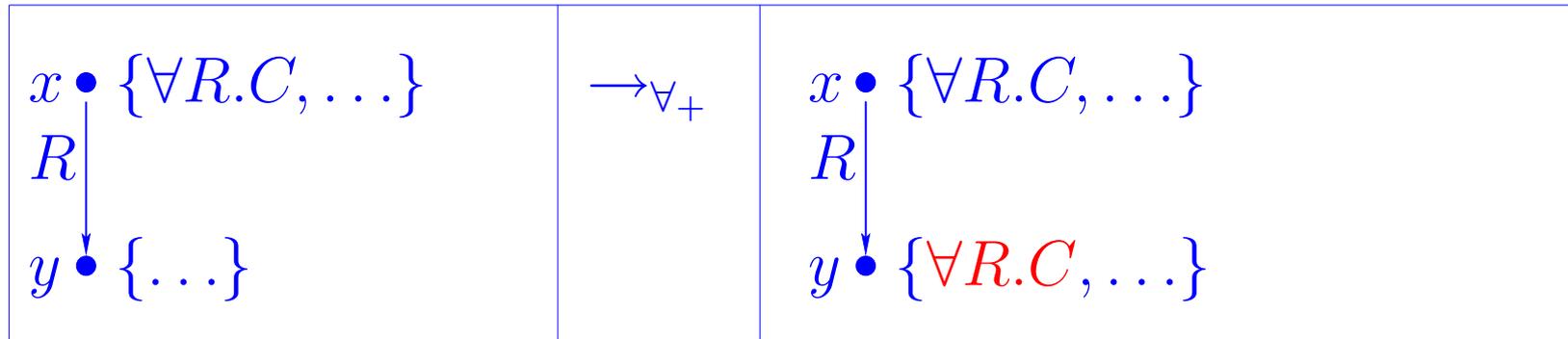
A tableau algorithm for \mathcal{ALC} with general TBoxes

- \sqcap -rule: if $C_1 \sqcap C_2 \in \mathcal{L}(x)$, $\{C_1, C_2\} \not\subseteq \mathcal{L}(x)$, **and x is not blocked**
then set $\mathcal{L}(x) = \mathcal{L}(x) \cup \{C_1, C_2\}$
- \sqcup -rule: if $C_1 \sqcup C_2 \in \mathcal{L}(x)$, $\{C_1, C_2\} \cap \mathcal{L}(x) = \emptyset$, **and x is not blocked**
then set $\mathcal{L}(x) = \mathcal{L}(x) \cup \{C\}$ for some $C \in \{C_1, C_2\}$
- \exists -rule: if $\exists S.C \in \mathcal{L}(x)$, x has no S -successor y with $C \in \mathcal{L}(y)$,
and x is not blocked
then create a new node y with $\mathcal{L}(\langle x, y \rangle) = \{S\}$ and $\mathcal{L}(y) = \{C\}$
- \forall -rule: if $\forall S.C \in \mathcal{L}(x)$, there is an S -successor y of x with $C \notin \mathcal{L}(y)$
and x is not blocked
then set $\mathcal{L}(y) = \mathcal{L}(y) \cup \{C\}$
- \mathcal{T} -rule: if $C_1 \dot{\sqsubseteq} C_2 \in \mathcal{T}$, $\text{NNF}(\neg C_1 \sqcup C_2) \notin \mathcal{L}(x)$
and x is not blocked
then set $\mathcal{L}(x) = \mathcal{L}(x) \cup \{\text{NNF}(\neg C_1 \sqcup C_2)\}$

Tableaux Rules for \mathcal{ALC}

$x \bullet \{C_1 \sqcap C_2, \dots\}$	\rightarrow_{\sqcap}	$x \bullet \{C_1 \sqcap C_2, C_1, C_2, \dots\}$
$x \bullet \{C_1 \sqcup C_2, \dots\}$	\rightarrow_{\sqcup}	$x \bullet \{C_1 \sqcup C_2, C, \dots\}$ for $C \in \{C_1, C_2\}$
$x \bullet \{\exists R.C, \dots\}$	\rightarrow_{\exists}	$x \bullet \{\exists R.C, \dots\}$ $R \downarrow$ $y \bullet \{C\}$
$x \bullet \{\forall R.C, \dots\}$ $R \downarrow$ $y \bullet \{\dots\}$	\rightarrow_{\forall}	$x \bullet \{\forall R.C, \dots\}$ $R \downarrow$ $y \bullet \{C, \dots\}$

Tableaux Rule for Transitive Roles



Where R is a transitive role (i.e., $(R^{\mathcal{I}})^+ = R^{\mathcal{I}}$)

- ➡ No longer naturally terminating (e.g., if $C = \exists R.\top$)
- ➡ Need blocking
 - Simple blocking suffices for \mathcal{ALC} plus transitive roles
 - I.e., do not expand node label if ancestor has superset label
 - More expressive logics (e.g., with inverse roles) need more sophisticated blocking strategies

Tableaux Algorithm — Example

Test satisfiability of $\exists S.C \sqcap \forall S.(\neg C \sqcup \neg D) \sqcap \exists R.C \sqcap \forall R.(\exists R.C)$ where R is a **transitive** role

Tableaux Algorithm — Example

Test satisfiability of $\exists S.C \sqcap \forall S.(\neg C \sqcup \neg D) \sqcap \exists R.C \sqcap \forall R.(\exists R.C)$ where R is a **transitive** role

$$\mathcal{L}(w) = \{\exists S.C \sqcap \forall S.(\neg C \sqcup \neg D) \sqcap \exists R.C \sqcap \forall R.(\exists R.C)\}$$

w

Tableaux Algorithm — Example

Test satisfiability of $\exists S.C \sqcap \forall S.(\neg C \sqcup \neg D) \sqcap \exists R.C \sqcap \forall R.(\exists R.C)$ where R is a **transitive** role

$$\mathcal{L}(w) = \{ \exists S.C \sqcap \forall S.(\neg C \sqcup \neg D) \sqcap \exists R.C \sqcap \forall R.(\exists R.C) \}$$

w

Tableaux Algorithm — Example

Test satisfiability of $\exists S.C \sqcap \forall S.(\neg C \sqcup \neg D) \sqcap \exists R.C \sqcap \forall R.(\exists R.C)$ where R is a **transitive** role

$$\mathcal{L}(w) = \{\exists S.C, \forall S.(\neg C \sqcup \neg D), \exists R.C, \forall R.(\exists R.C)\}$$

w

Tableaux Algorithm — Example

Test satisfiability of $\exists S.C \sqcap \forall S.(\neg C \sqcup \neg D) \sqcap \exists R.C \sqcap \forall R.(\exists R.C)$ where R is a **transitive** role

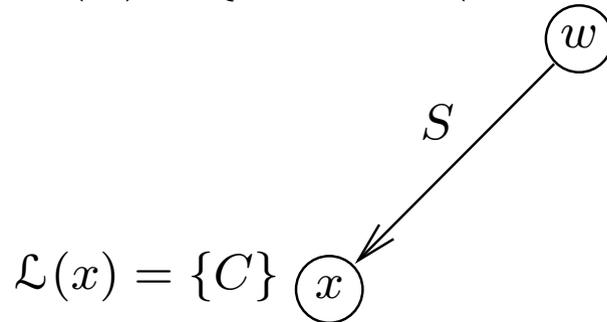
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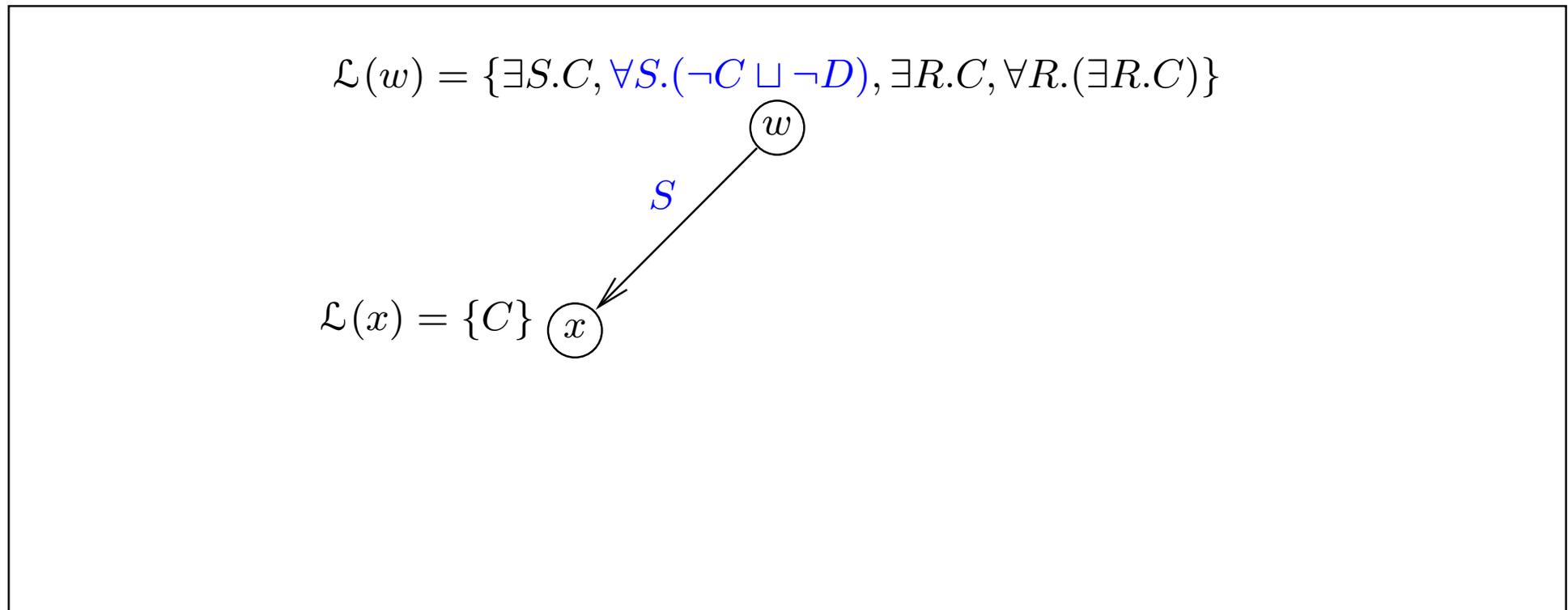
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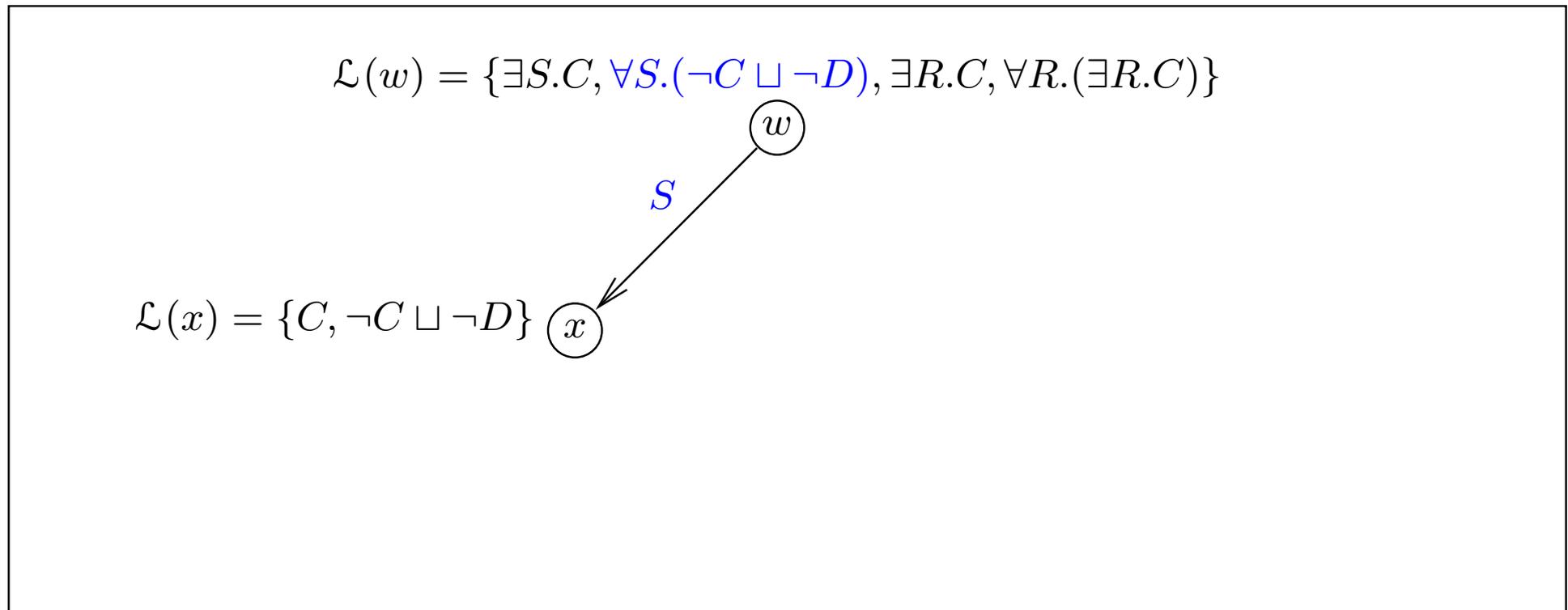
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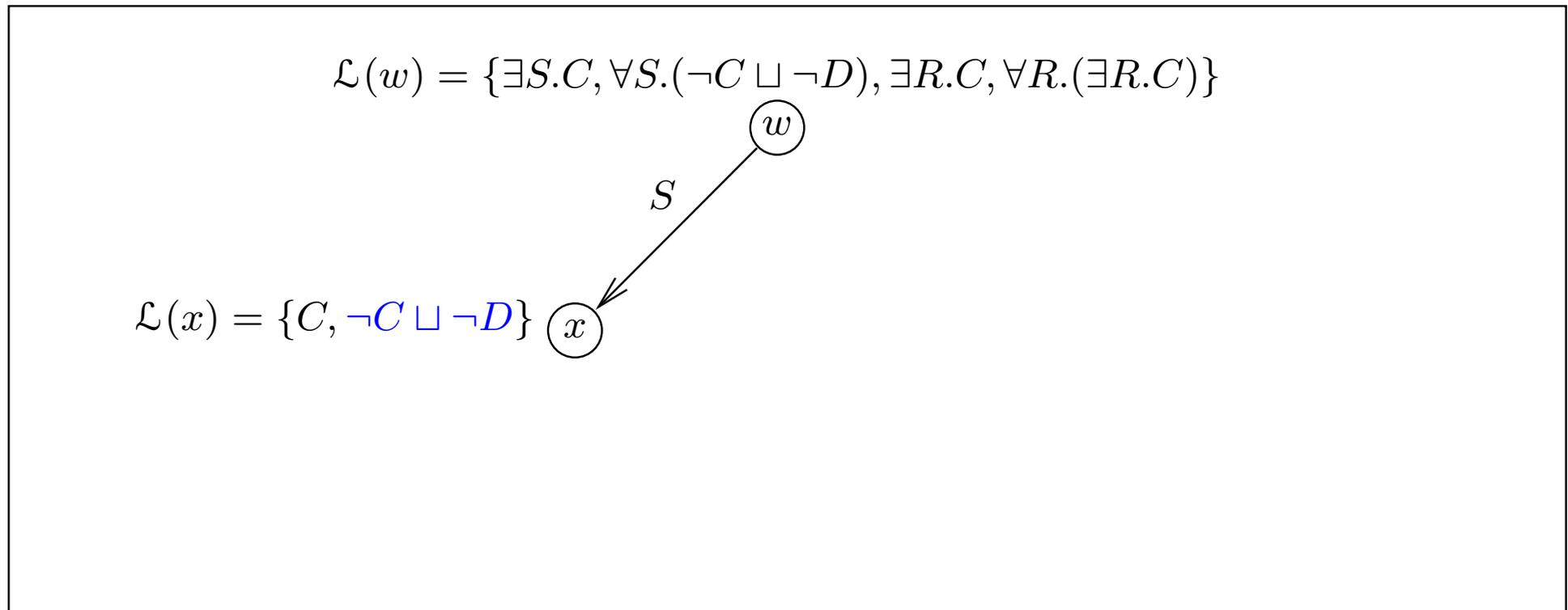
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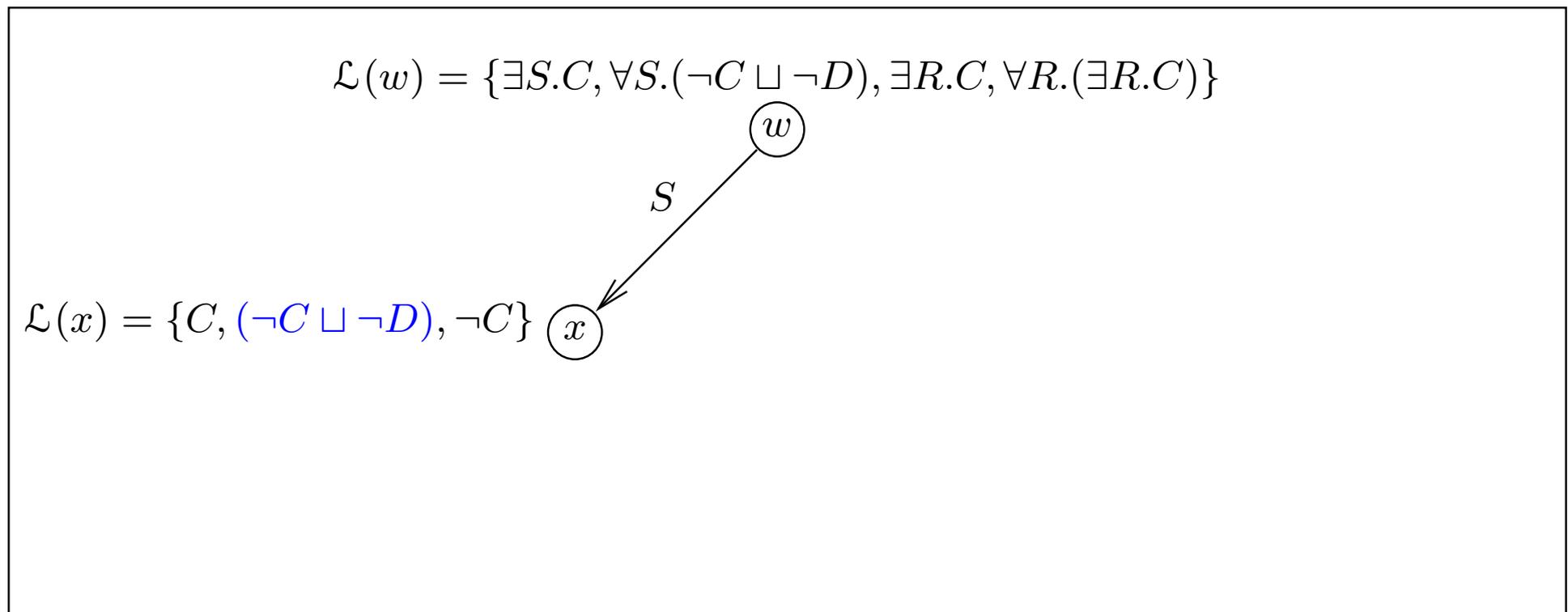
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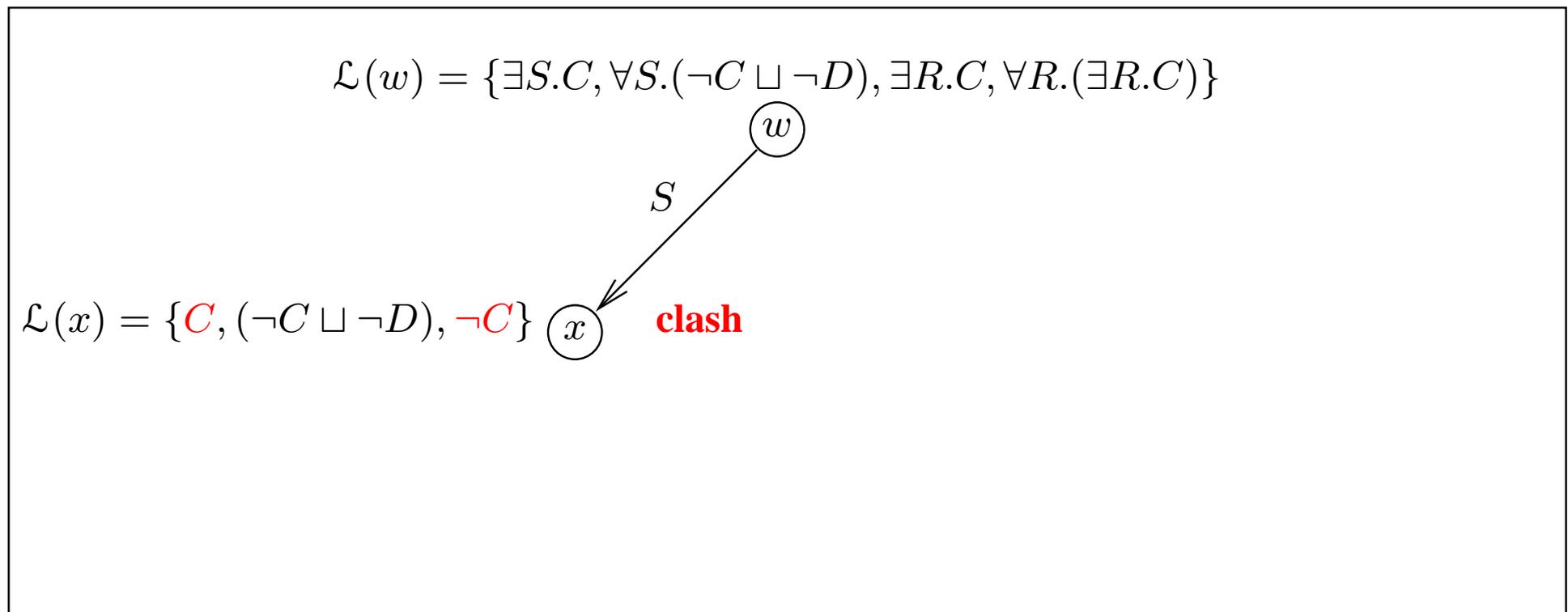
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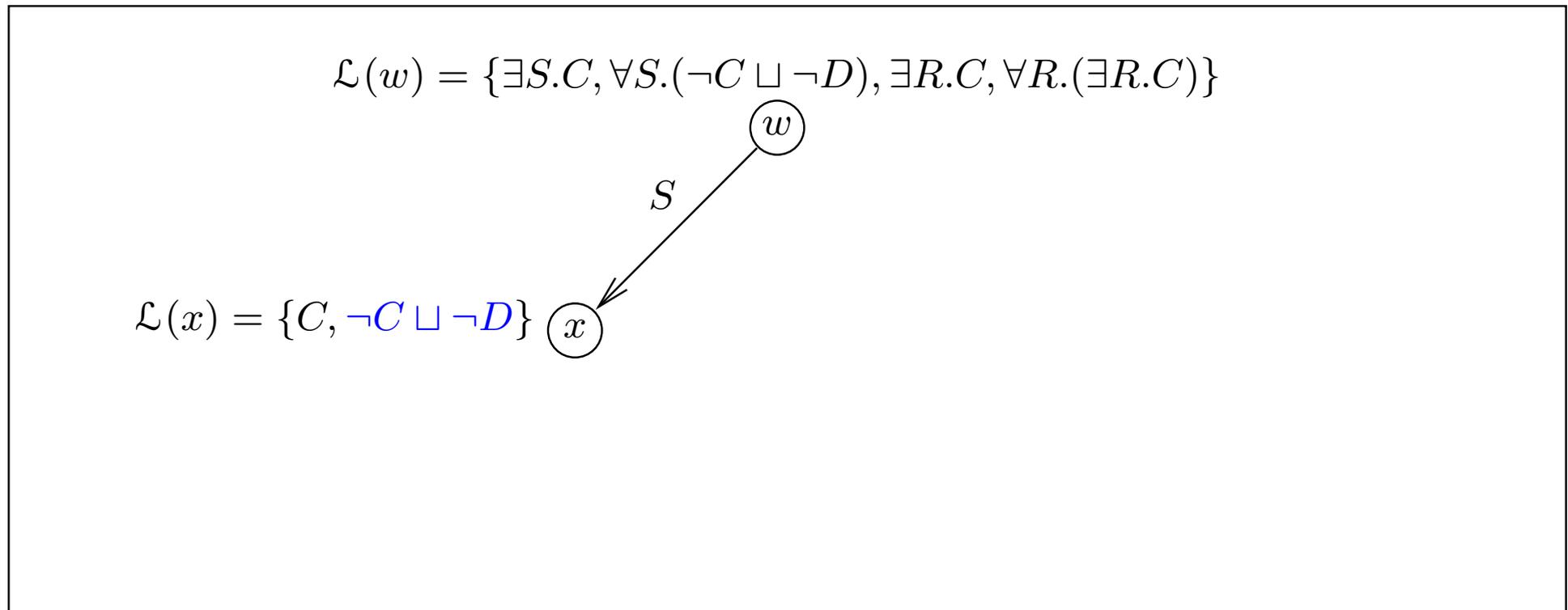
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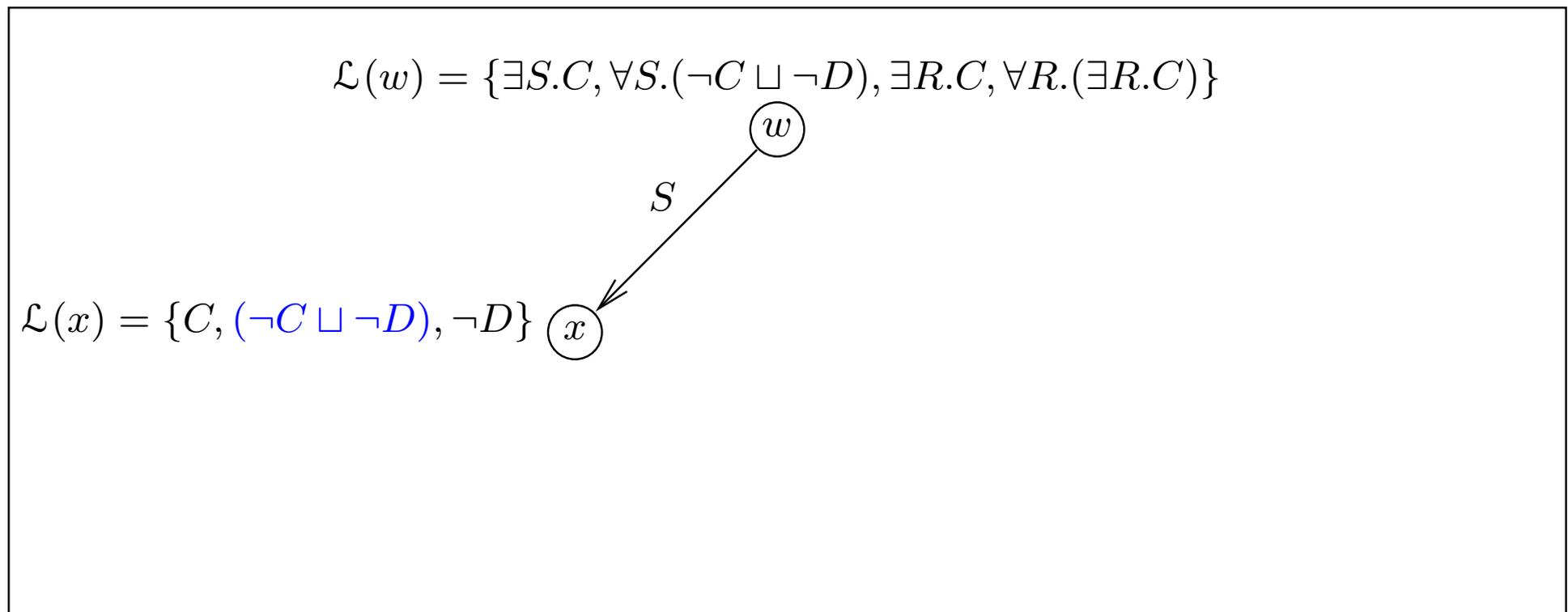
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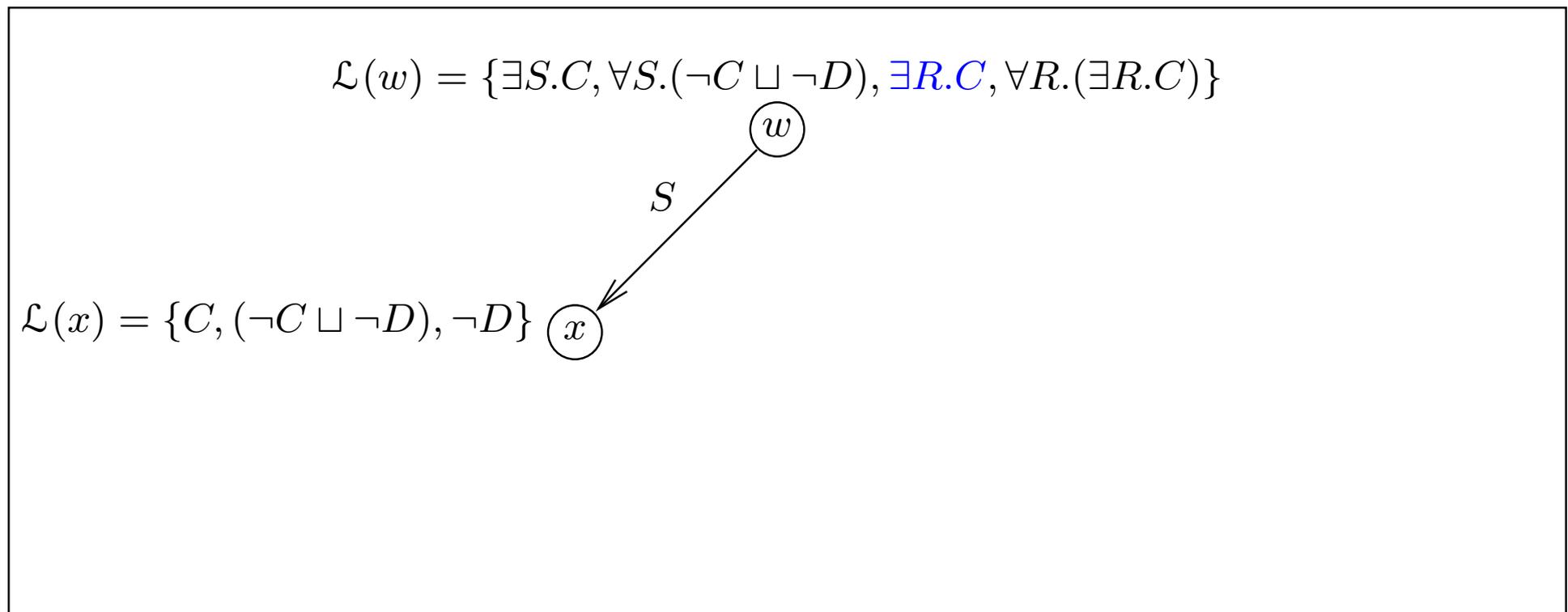
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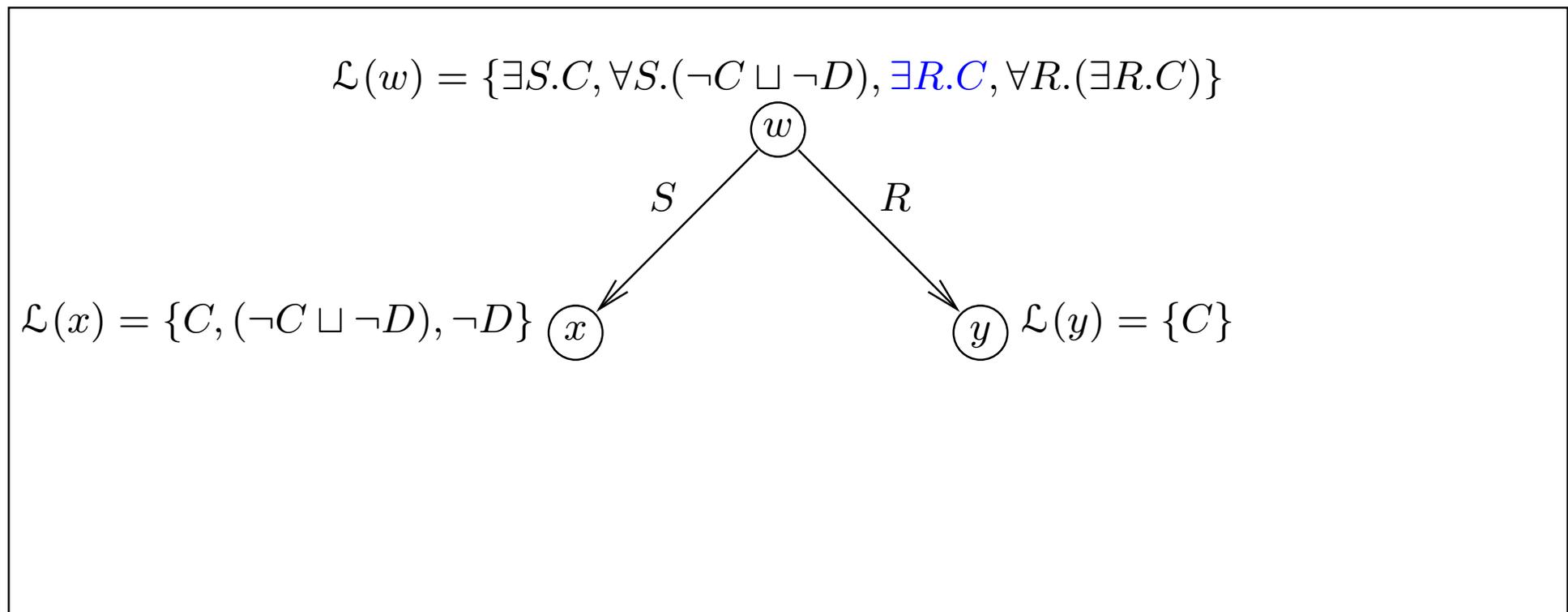
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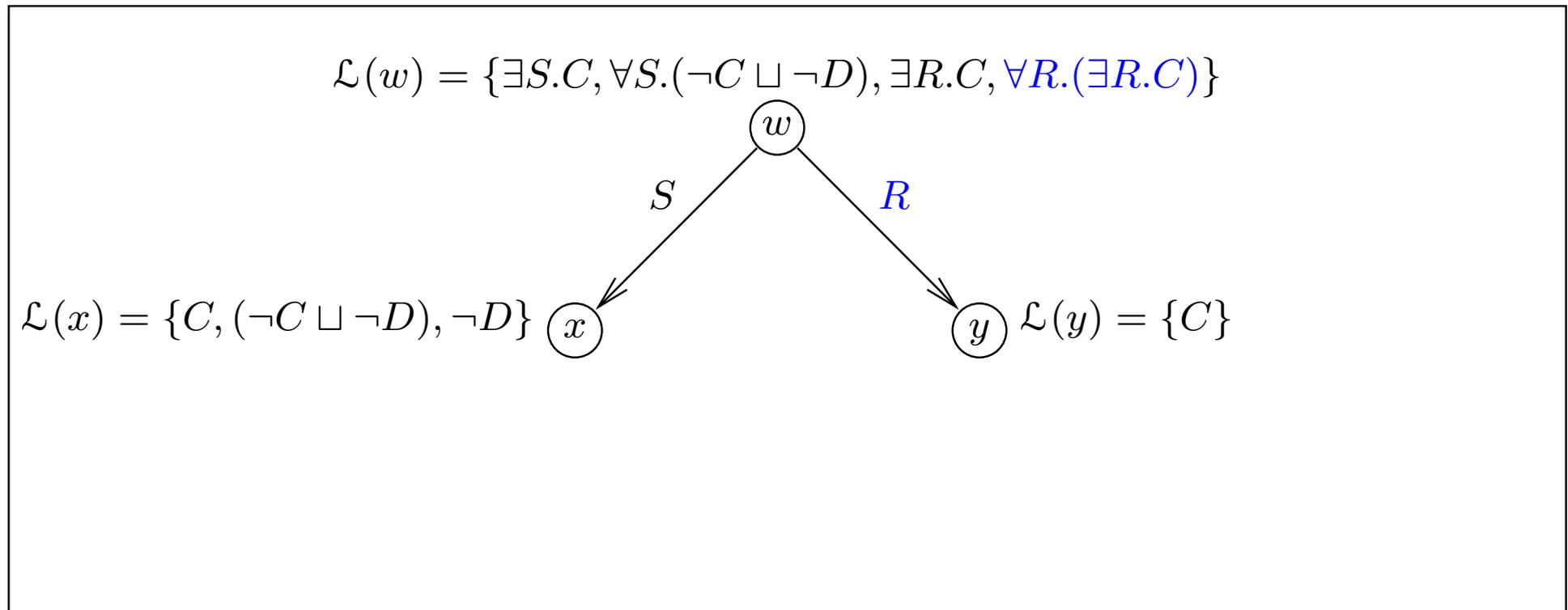
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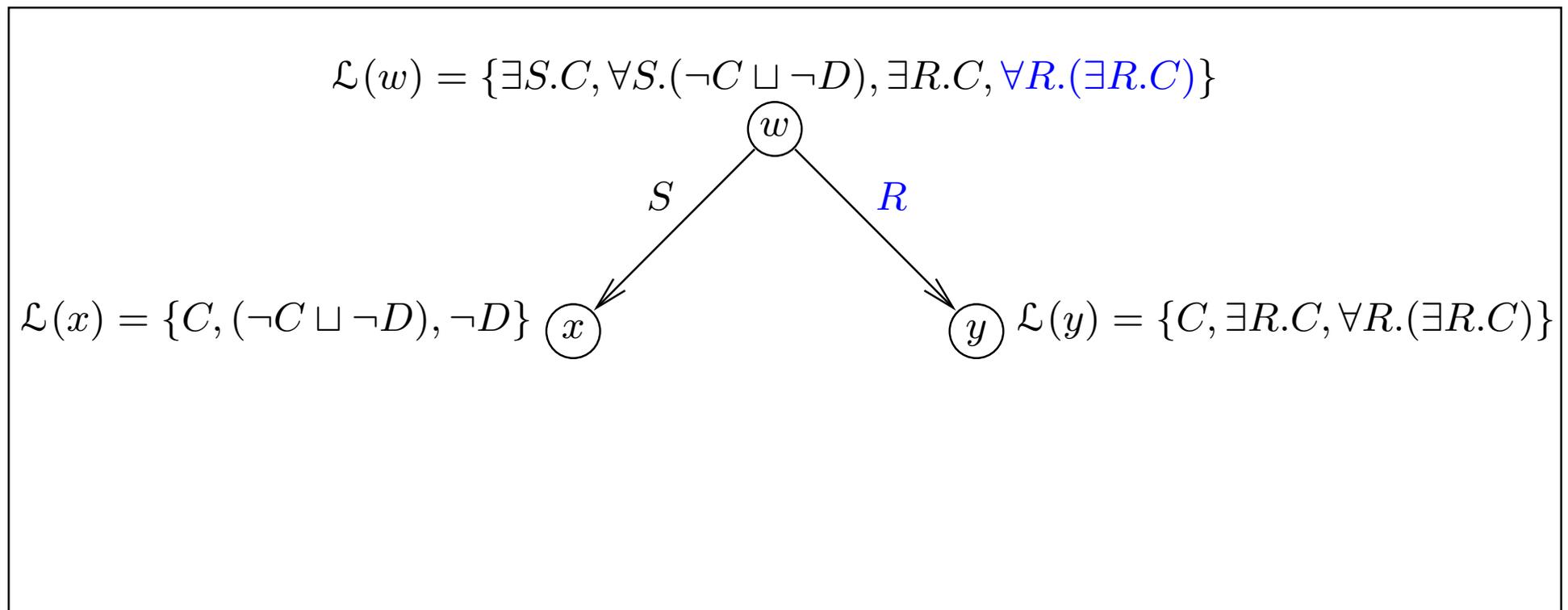
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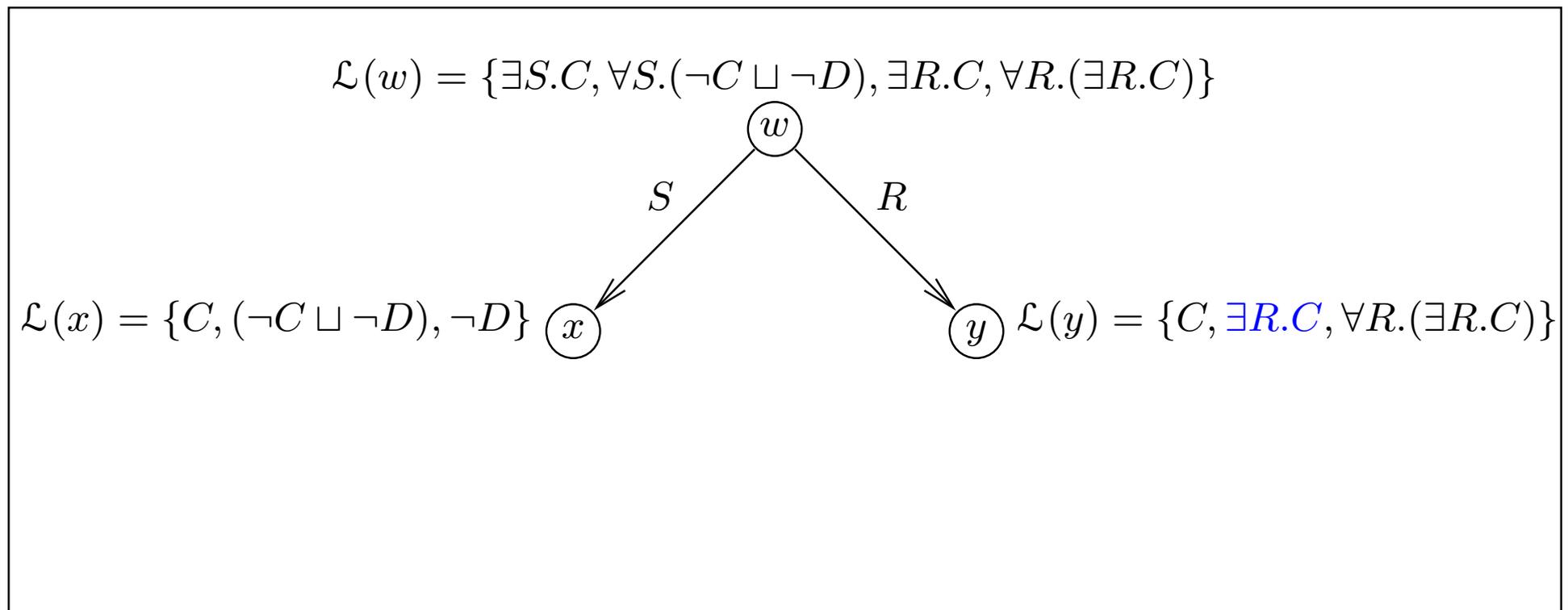
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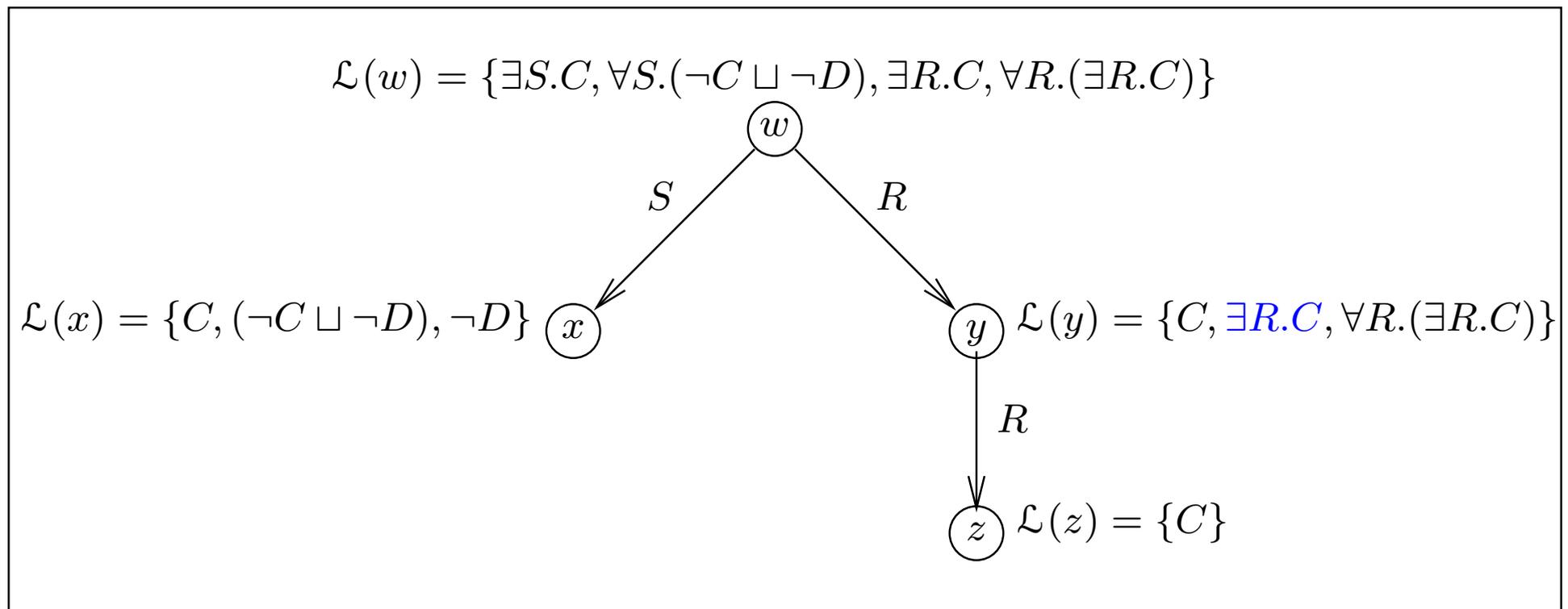
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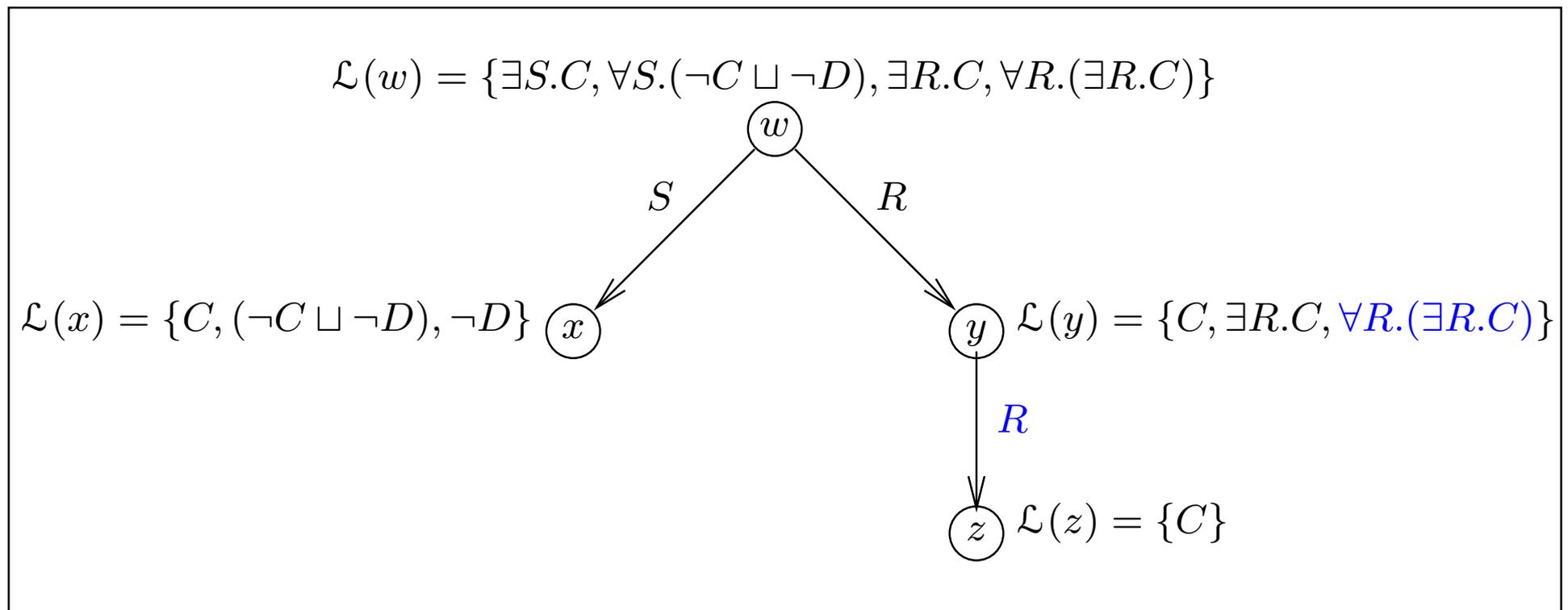
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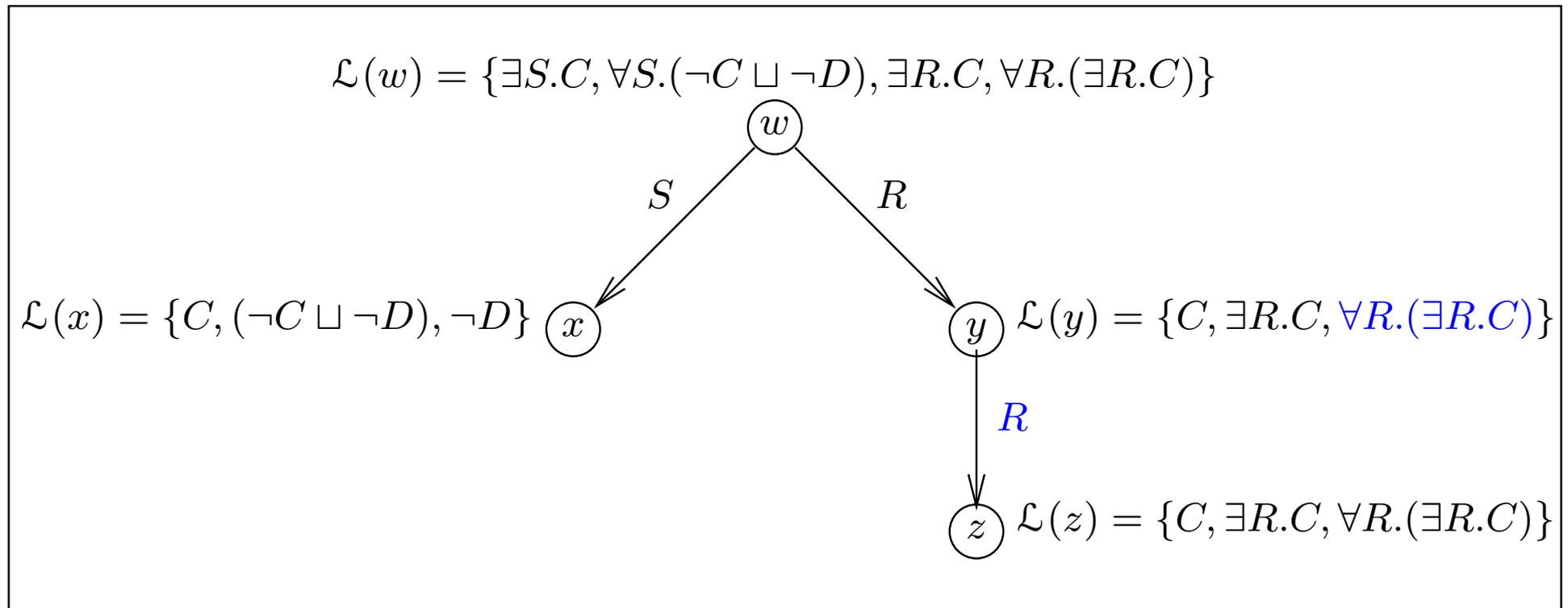
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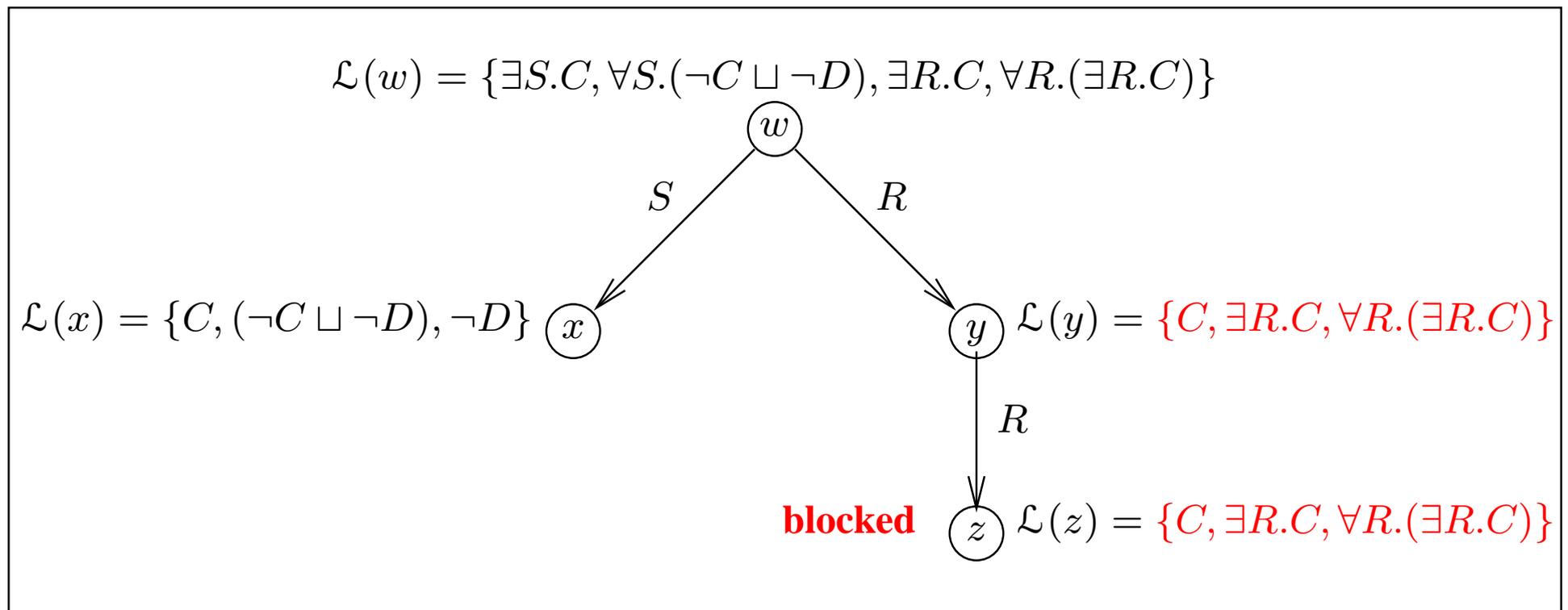
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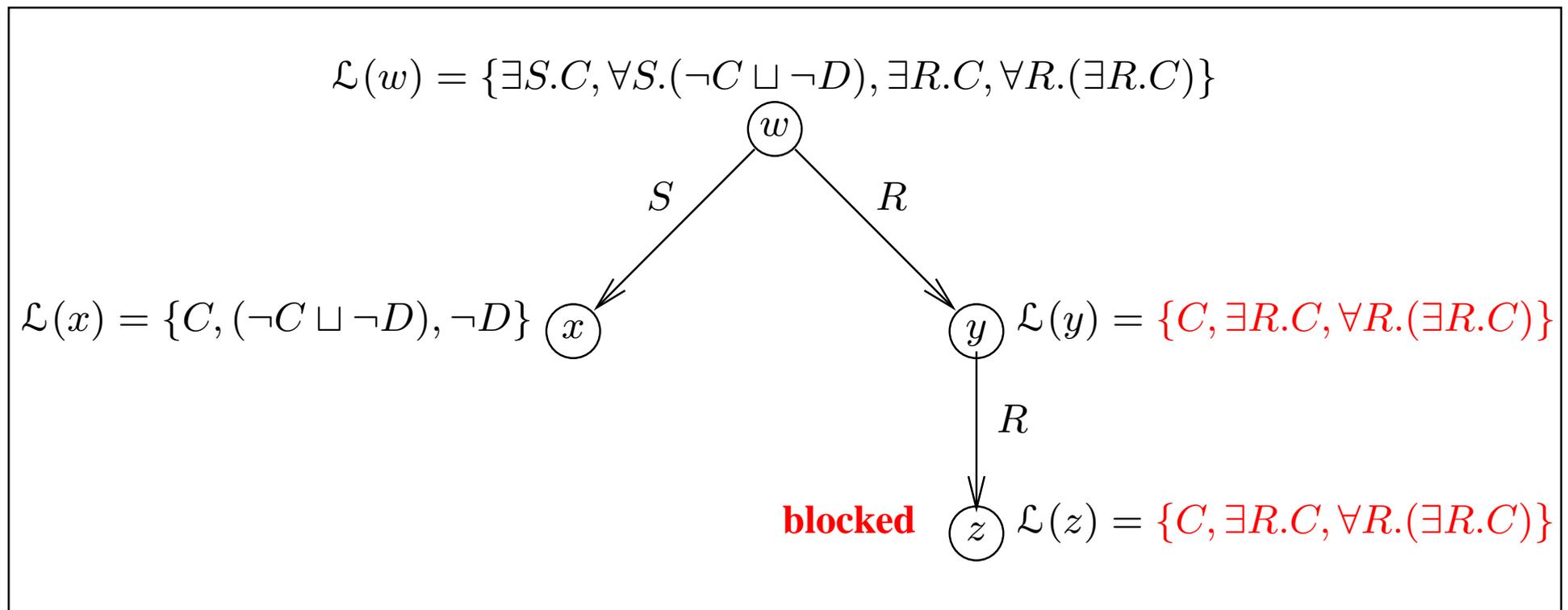
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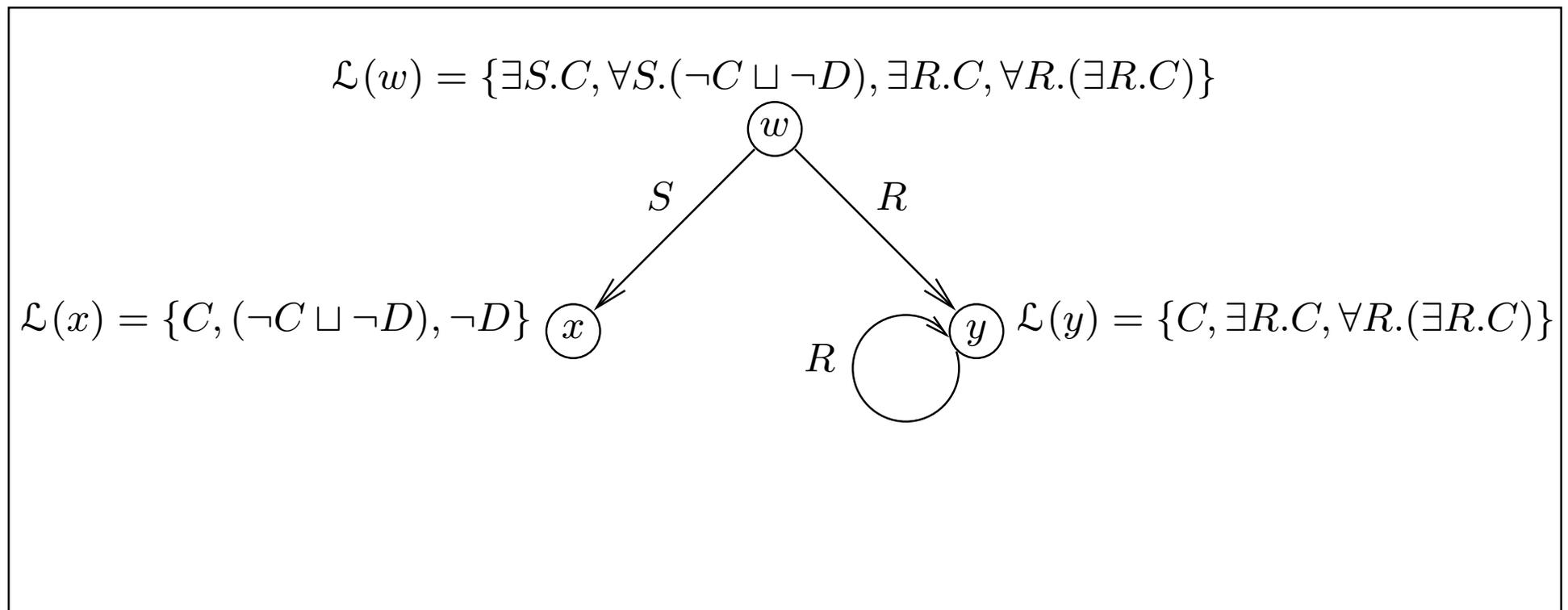
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Concept is **satisfiable**: \mathbb{T} corresponds to **model**

Tableaux Algorithm — Example

Test satisfiability of $\exists S.C \sqcap \forall S.(\neg C \sqcup \neg D) \sqcap \exists R.C \sqcap \forall R.(\exists R.C)$ where R is a **transitive** role



Concept is **satisfiable**: \mathbb{T} corresponds to **model**

Properties of our tableau algorithm for \mathcal{ALC} with TBoxes

Lemma: Let \mathcal{T} be a general \mathcal{ALC} -Tbox and C_0 an \mathcal{ALC} -concept. Then

1. the algorithm terminates when applied to \mathcal{T} and C_0 and
2. the rules can be applied such that they generate a clash-free and complete completion tree iff C_0 is satisfiable w.r.t. \mathcal{T} .

- Corollary:**
1. Satisfiability of \mathcal{ALC} -concept w.r.t. TBoxes is decidable
 2. \mathcal{ALC} with TBoxes has the finite model property
 3. \mathcal{ALC} with TBoxes has the tree model property

Proof of the Lemma: Termination

(1) termination is, again, due to the following properties: let $n = |C_0| + |C_{\mathcal{T}}|$ and

$$\text{sub}(C_0, \mathcal{T}) = \text{sub}(C_0) \cup \bigcup_{C \dot{\subseteq} D \in \mathcal{T}} \text{sub}(C) \cup \text{sub}(D)$$

1. the c- tree is built in a **monotonic way**:
each rule either extends node labels or adds a node (with a label)
2. node labels are restricted to subsets of $\text{sub}(C_0, \mathcal{T})$ and $\# \text{sub}(C_0, \mathcal{T}) \leq n$
3. the **breadth** of the c-tree is bounded by n :
at most 1 successor per $\exists R.C \in \text{sub}(C_0, \mathcal{T})$
4. the **depth** of the c-tree is bounded:
on a path of length 2^n , blocking occurs, and thus it does not get longer

Important: in the presence of TBoxes, c-tree can be of **exponential depth** whereas without TBoxes, depth was linearly bounded

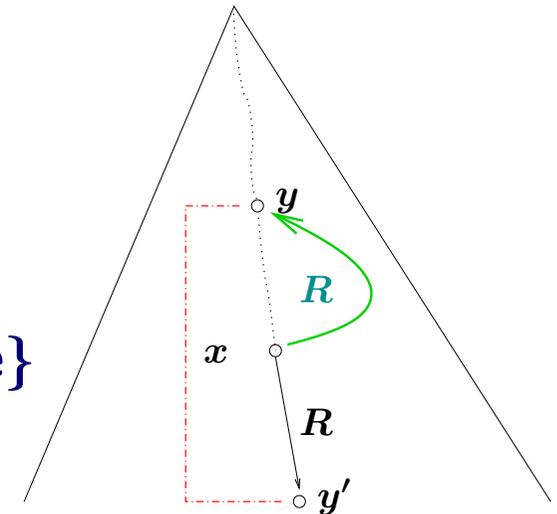
Proof of the Lemma: Soundness

(2) let the algorithm stop with a complete and clash-free c-tree.
 Again, from this, we define an interpretation:

$$\Delta^{\mathcal{I}} := \{x \mid x \text{ is a node in } \mathcal{T}, x \text{ is not blocked}\}$$

$$A^{\mathcal{I}} := \{x \in \Delta^{\mathcal{I}} \mid A \in \mathcal{L}(x)\} \text{ for concept names } A$$

$$R^{\mathcal{I}} := \{\langle x, y \rangle \in \Delta^{\mathcal{I}^2} \mid y \text{ is an } R\text{-succ of } x \text{ in c-tree or } y \text{ blocks an } R\text{-succ of } x \text{ in c-tree}\}$$



and show, by induction on the structure of concepts, for all $x \in \Delta^{\mathcal{I}}$, $D \in \text{sub}(C_0, \mathcal{T})$:

$$D \in \mathcal{L}(x) \text{ implies } x \in D^{\mathcal{I}}.$$

This implies that \mathcal{I} is indeed a model of C_0 and \mathcal{T} because

- (a) C_0 is in the label of the root node which cannot be blocked (!) and
- (b) $\neg C \sqcup D$ is in the label of each node, for each $C \sqsubseteq D \in \mathcal{T}$

Proof of the Lemma: Completeness

(3) Let C_0 be satisfiable w.r.t. \mathcal{T} and \mathcal{I} a model of them with $a_0 \in C_0^{\mathcal{I}}$.

Use \mathcal{I} to steer the application of the (only non-deterministic) \sqcup -rule:

Inductively define a total mapping π : nodes of completion tree $\rightarrow \Delta^{\mathcal{I}}$, start with $\pi(x_0) = a_0$, and show that

each rule can be applied in such a way that $(*)$ is preserved

if $C \in \mathcal{L}(x)$, then $\pi(x) \in C^{\mathcal{I}}$ (*)

if y is an R -succ. of x , then $\langle \pi(x), \pi(y) \rangle \in R^{\mathcal{I}}$

- easy for \sqcap -, \mathcal{T} -, and \forall -rule,
 - for \exists -rule, we need to extend π to the newly created R -successor
 - for \sqcup -rule, if $C_1 \sqcup C_2 \in \mathcal{L}(x)$, $(*)$ implies that $\pi(x) \in (C_1 \sqcup C_2)^{\mathcal{I}}$
 \rightsquigarrow we can choose C_i with $\pi(x) \in C_i^{\mathcal{I}}$ to add to $\mathcal{L}(x)$ and thus preserve $(*)$
- \rightsquigarrow easy to see: **$(*)$ implies that c-tree is clash-free**

Proof of the Lemma: Harvest

Look again at the model \mathcal{I} constructed for a clash-free, complete c-tree:

- \mathcal{I} is
- **finite** because c-tree has finitely many nodes
 - but it is **not a tree** if blocking occurs

Hence we get Corollary (2) for free from our proof:

C_0 is satisfiable

- \rightsquigarrow tableau algorithm stops with clash-free, complete c-tree
- $\rightsquigarrow C_0$ has a finite model.

To obtain Corollary (3), the tree model property, we must work a bit more:

- \rightsquigarrow build the model in a different way, “unravel” the c-tree into an infinite tree
- intuitively, instead of going to a blocked node, go to a copy of its blocking node

A tableau algorithm for \mathcal{ALC} with general TBoxes: Summary

The tableau algorithm presented here

- decides satisfiability of \mathcal{ALC} -concepts w.r.t. TBoxes, and thus also
- decides subsumption of \mathcal{ALC} -concepts w.r.t. TBoxes
- uses **blocking** to ensure termination, and
- is **non-deterministic** due to the \rightarrow_{\sqcup} -rule
- in the worst case, it builds a tree of depth exponential in the size of the input, and thus of double exponential size. Hence it runs in (worst case) $2N\text{ExpTime}$,
- can be implemented in various ways,
 - order/priorities of rules
 - data structure
 - etc.
- is amenable to optimisations – more on this next week

Next, we could

- discuss implementation issues for our tableau algorithms, e.g.,
 - datastructures,
 - more efficient (i.e., less strict) blocking conditions,
 - a good strategy for the order of rule applications,
 - how to “determinise” our non-deterministic algorithm: e.g., backtracking
 - etc.
- discuss other reasoning techniques for DLs
- analyse computational complexity of DLs
- further extend our tableau algorithm for more expressive DLs with one more expressive means

Naive Implementations

Problems include:

 **Space** usage

- Storage required for tableaux datastructures
- Rarely a serious problem in practice
- But problems can arise with inverse roles and cyclical KBs

 **Time** usage

- Search required due to non-deterministic expansion
- **Serious** problem in practice
- Mitigated by:
 - Careful **choice of algorithm**
 - Highly **optimised implementation**

Careful Choice of Algorithm

- ➔ **Transitive roles** instead of transitive closure
 - Deterministic expansion of $\exists R.C$, even when $R \in \mathbf{R}_+$
 - (Relatively) simple blocking conditions
 - Cycles **always** represent (part of) valid cyclical models
- ➔ **Direct algorithm**/implementation instead of encodings
 - GCI axioms can be used to “encode” additional operators/axioms
 - Powerful technique, particularly when used with FL closure
 - Can encode cardinality constraints, inverse roles, range/domain, ...
 - E.g., $(\text{domain } R.C) \equiv \exists R.T \sqsubseteq C$
 - (FL) encodings introduce (large numbers of) axioms
 - **BUT** even simple domain encoding is **disastrous** with large numbers of roles

Dependency Directed Backtracking

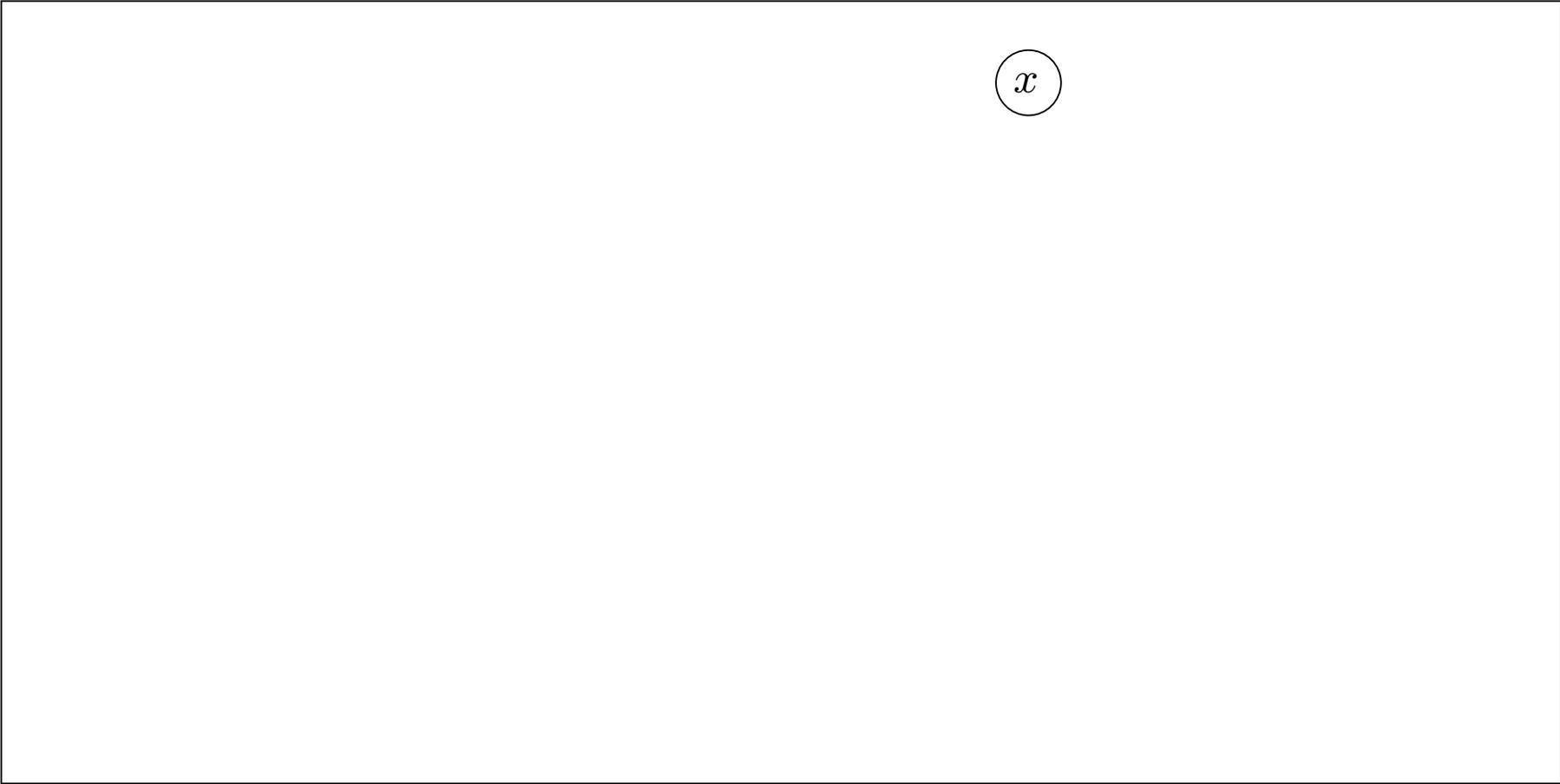
- ➡ Allows **rapid recovery** from bad branching choices
- ➡ Most commonly used technique is **backjumping**
 - Tag concepts introduced at **branch points** (e.g., when expanding disjunctions)
 - Expansion rules combine and **propagate tags**
 - On discovering a clash, **identify** most recently introduced concepts involved
 - **Jump back** to relevant branch points **without exploring** alternative branches
 - Effect is to **prune** away part of the search space
- ➡ **Highly effective** — essential for usable system
 - E.g., GALEN KB, 30s (with) → months++ (without)

Backjumping

E.g., if $\exists R. \neg A \sqcap \forall R. (A \sqcap B) \sqcap (C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \subseteq \mathcal{L}(x)$

Backjumping

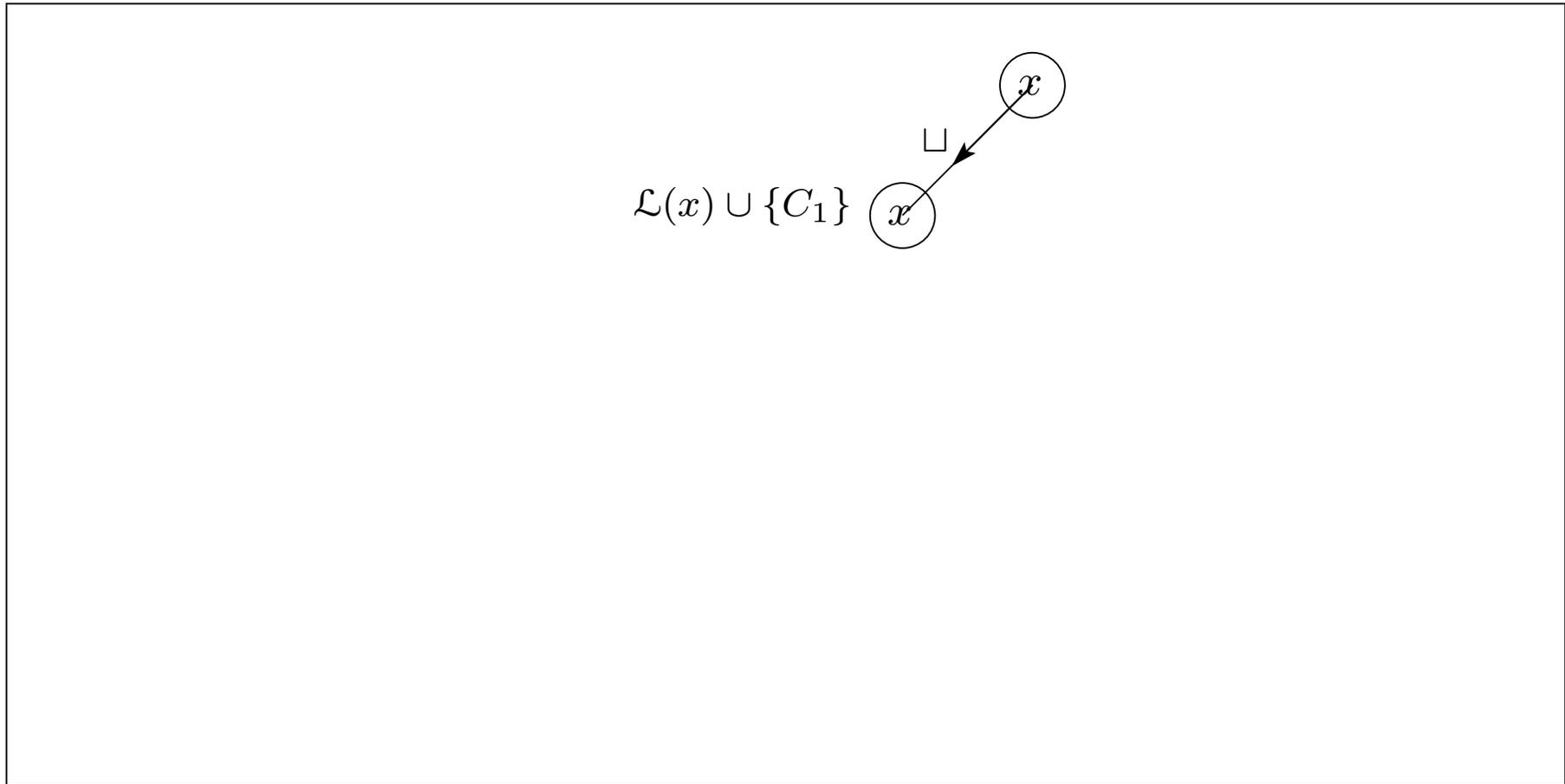
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x

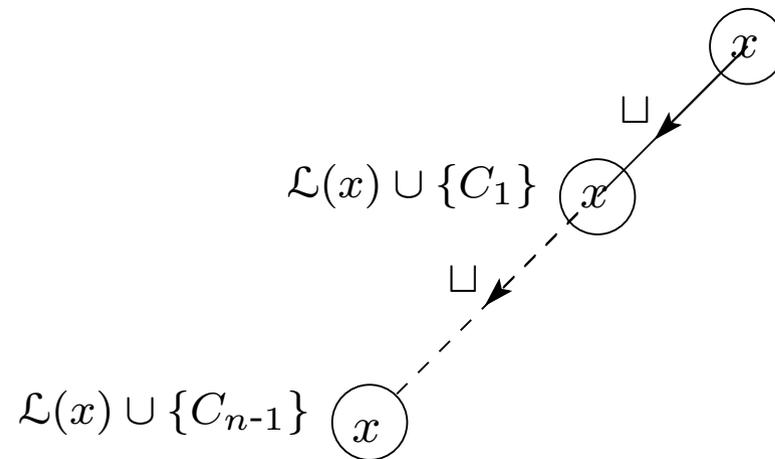
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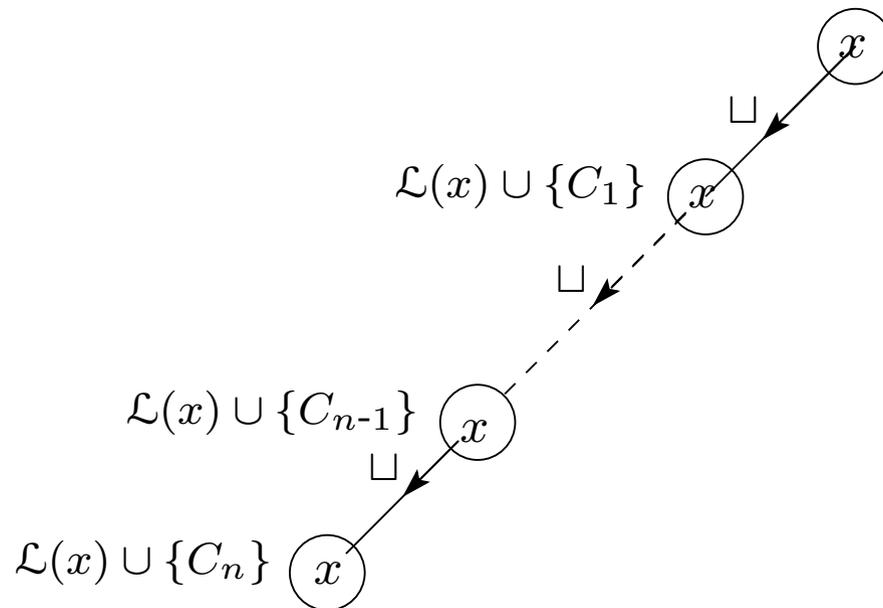
Backjumping

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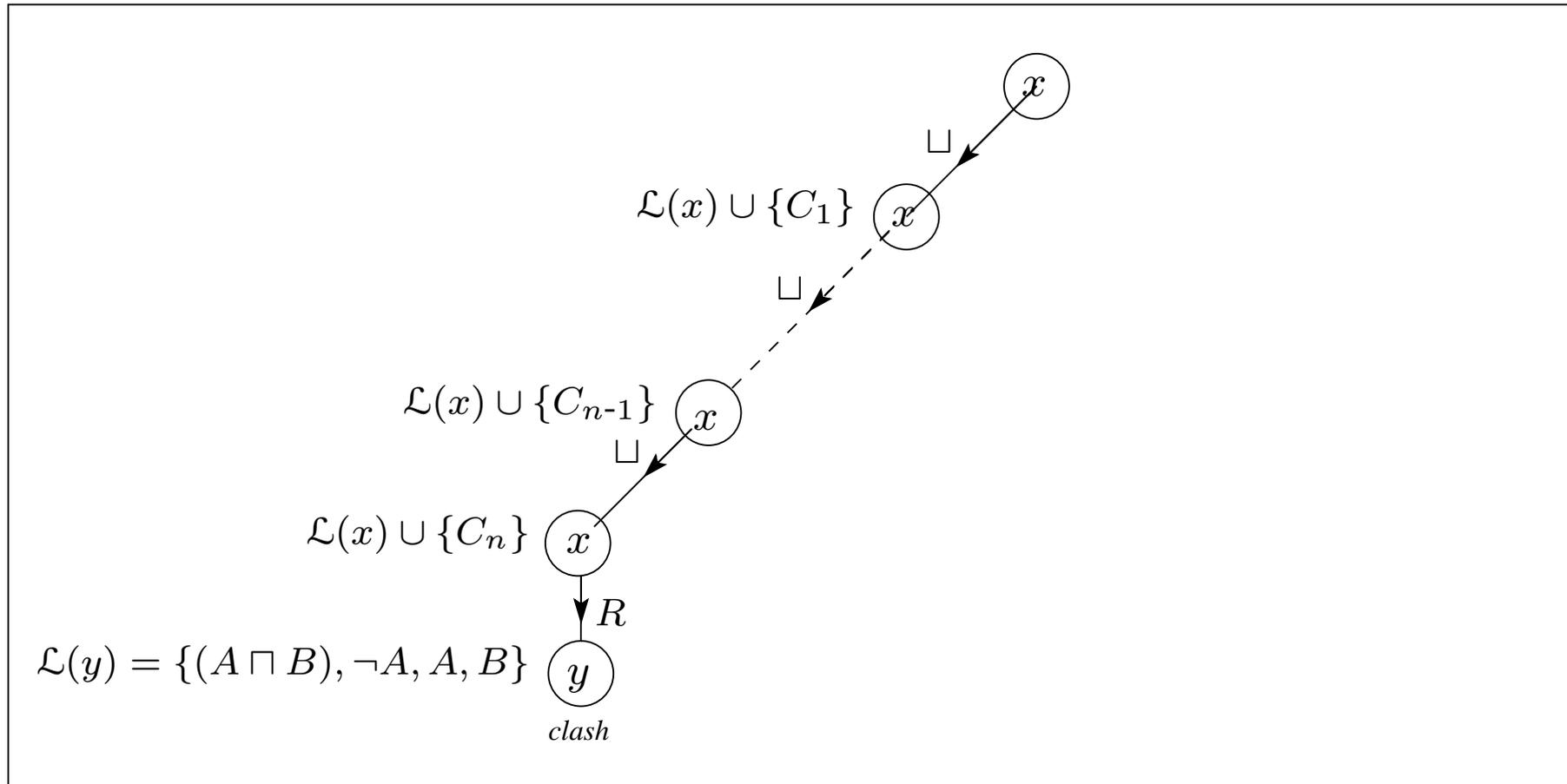
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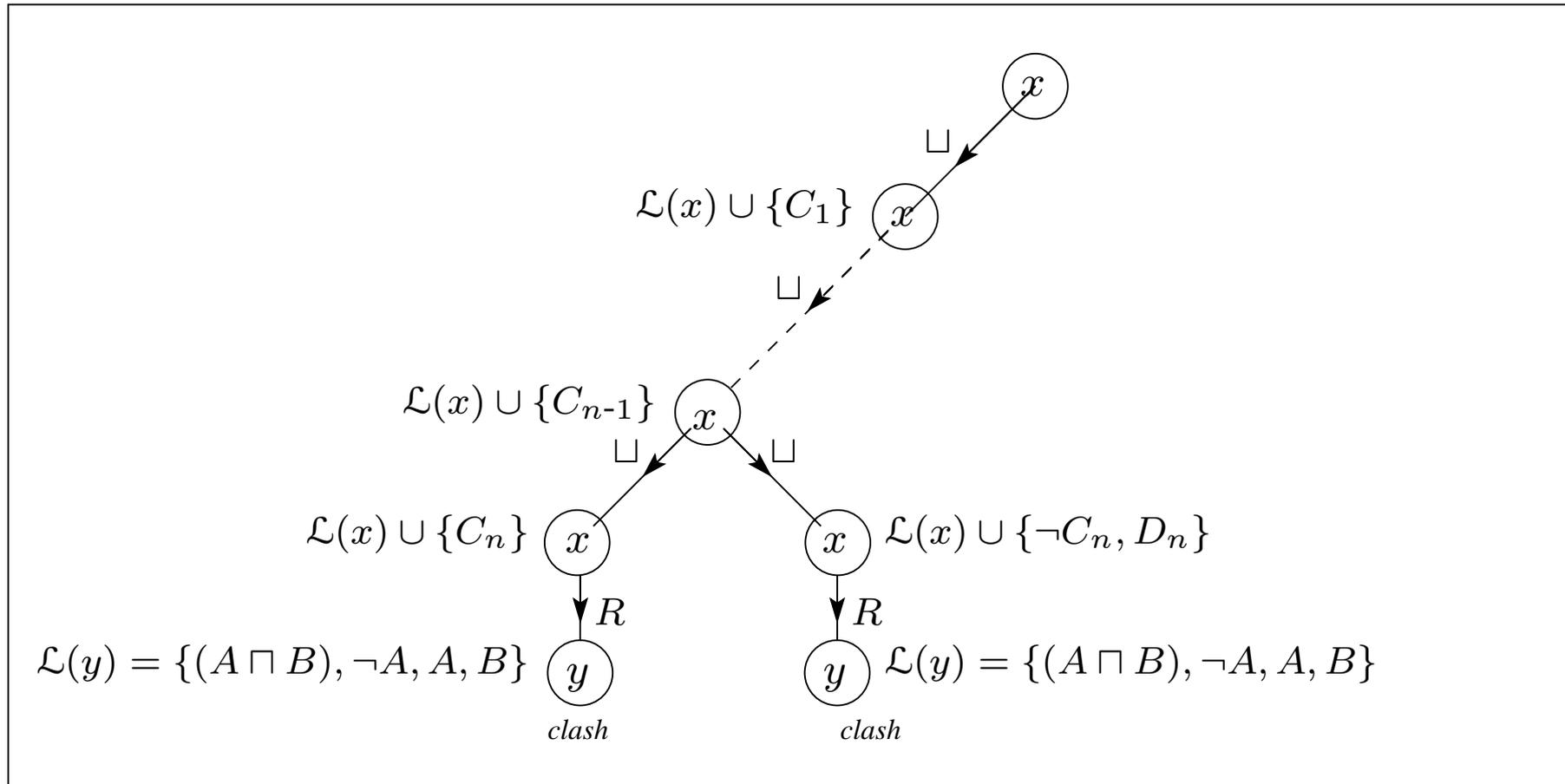
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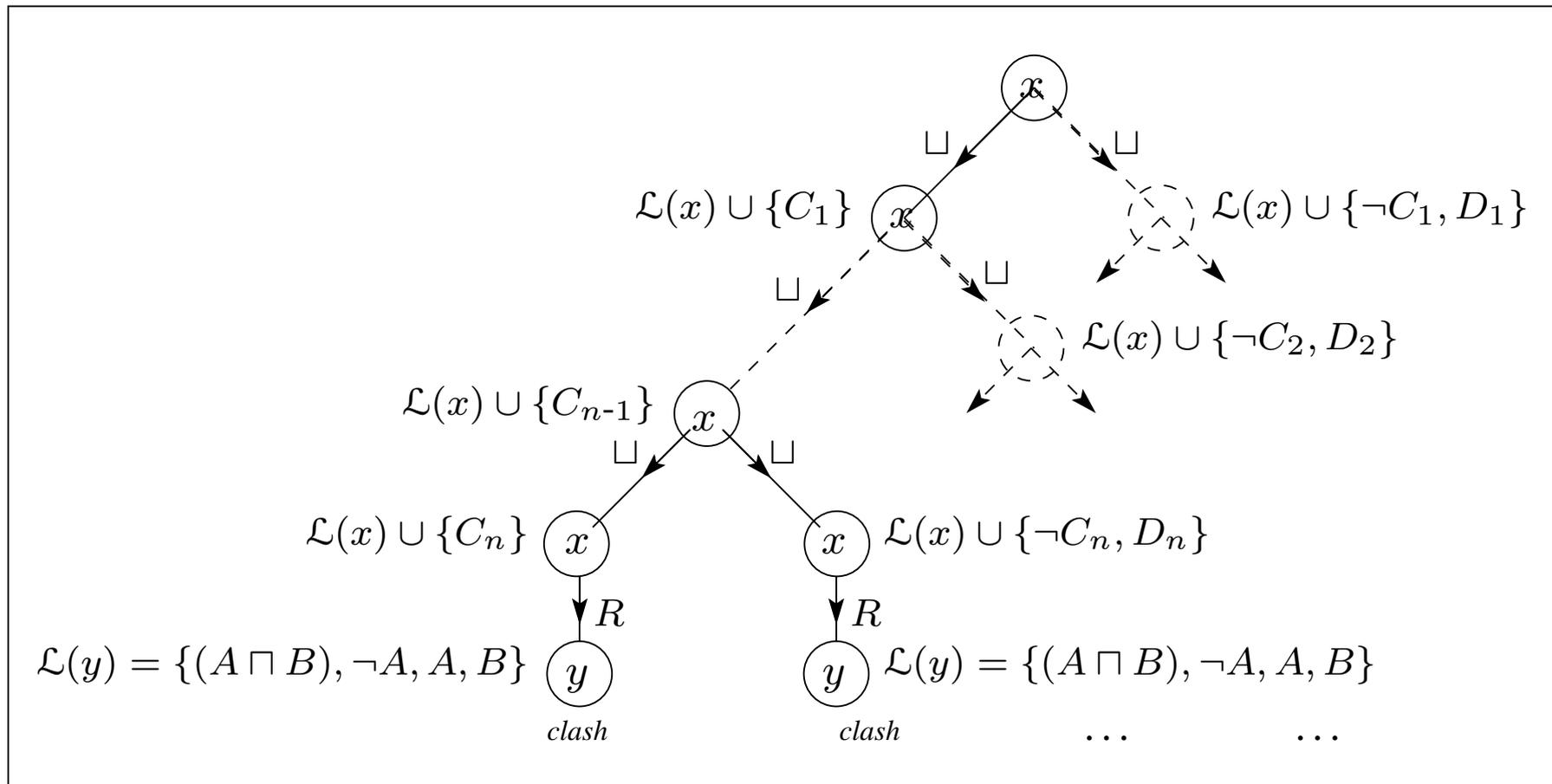
Backjumping

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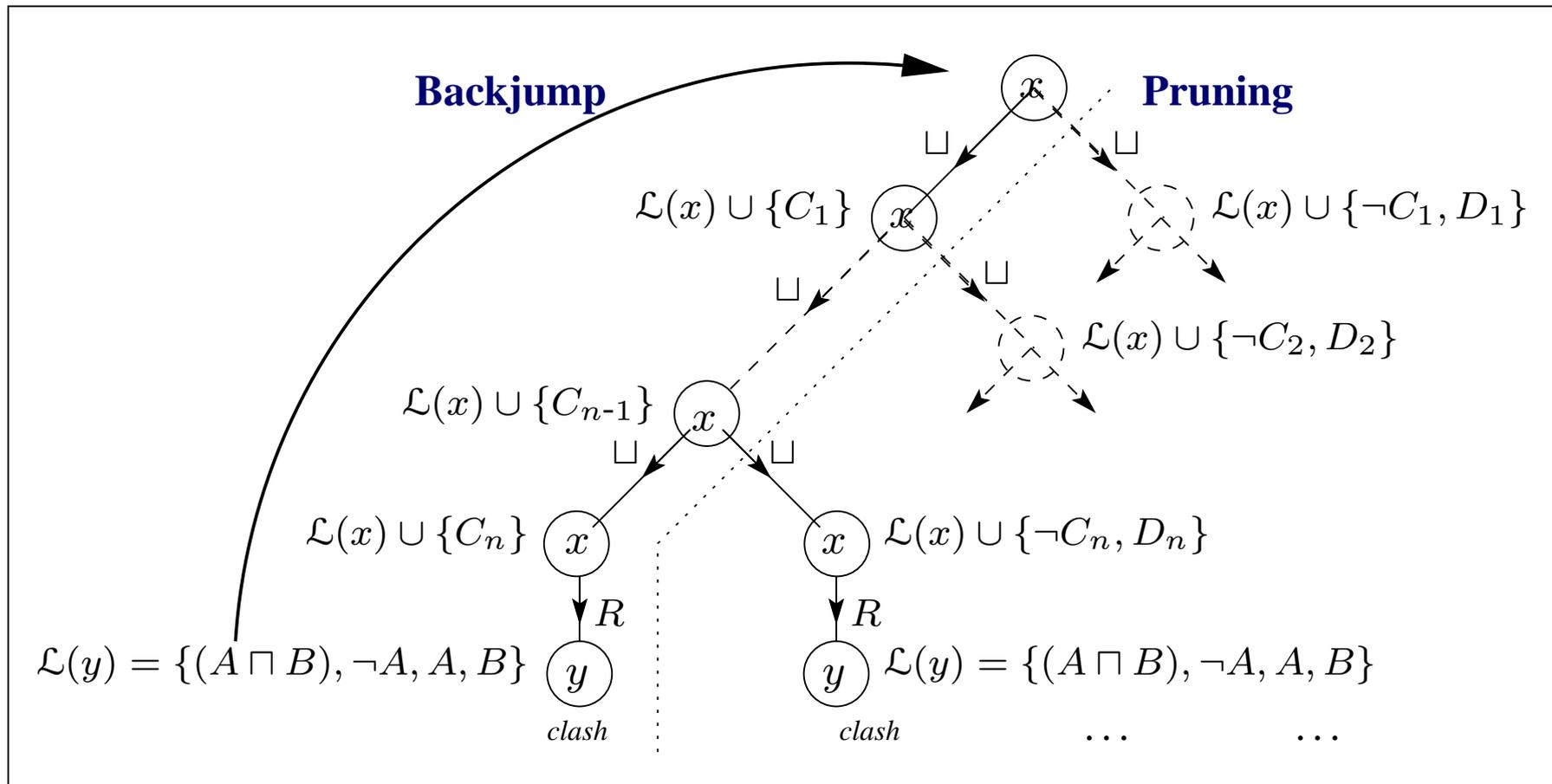
Backjumping

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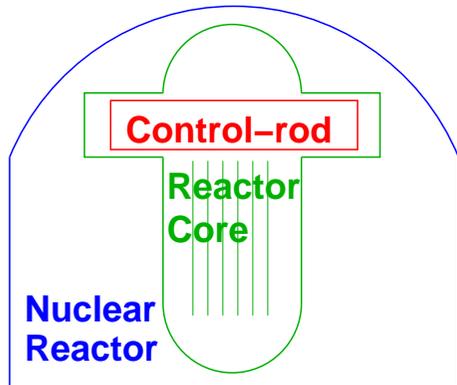


Backjumping

E.g., if $\exists R. \neg A \sqcap \forall R. (A \sqcap B) \sqcap (C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \subseteq \mathcal{L}(x)$



Inverse Roles



Consider the following TBox

$$\begin{aligned} \text{Control-rod} &\sqsubseteq \text{Device} \sqcap \exists \text{part-of.Reactor-core} \\ \text{Reactor-core} &\sqsubseteq \text{Device} \sqcap \exists \text{has-part.Control-rod} \sqcap \\ &\quad \exists \text{part-of.N-reactor}, \\ \text{Reactor-core} \sqcap \exists \text{has_part.Faulty} &\sqsubseteq \text{Dangerous}, \end{aligned}$$

Now, w.r.t. such a TBox, we find that

$\text{Control_rod} \sqcap \text{Faulty}$ should be subsumed by $\exists \text{part-of.Dangerous}$

But this is not true: no interaction between part-of and has-part!

\rightsquigarrow also allow for $\exists R^- . C$ and $\forall R^- . C$, where $(R^-)^{\mathcal{I}} = \{\langle y, x \rangle \mid \langle x, y \rangle \in R^{\mathcal{I}}\}$

A tableau algorithm for \mathcal{ALCI} with general TBoxes

\mathcal{ALCI} is the extension of \mathcal{ALC} with inverse roles R^- in the place of role names:

$$(R^-)^{\mathcal{I}} := \{ \langle y, x \rangle \mid \langle x, y \rangle \in R^{\mathcal{I}} \}$$

Example: does $\forall \text{parent}.\forall \text{child}.\text{Blond} \sqsubseteq \text{Blond}$ w.r.t. $\{ \top \dot{\sqsubseteq} \exists \text{parent}.\top \}$?

does $\forall \text{parent}.\forall \text{parent}^-. \text{Blond} \sqsubseteq \text{Blond}$ w.r.t. $\{ \top \dot{\sqsubseteq} \exists \text{parent}.\top \}$?

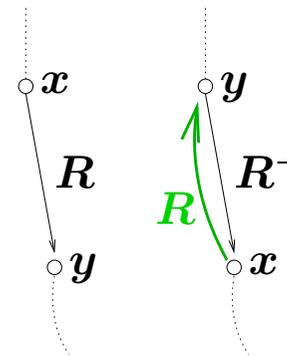
Example: is $C_0 = \exists R.\exists S.\exists T.A$ satisf. w.r.t. $\{ C \dot{\sqsubseteq} \exists R.C \sqcap \forall R.B$
 $\top \dot{\sqsubseteq} \forall T^-. \forall S^-. \forall R^-. C \}$?

Clear: inverse roles \rightsquigarrow tableau algorithm must reason *up and down* edges

A tableau algorithm for \mathcal{ALCI} with general TBoxes

Modifications necessary to handle inverse roles:

- ① extend edge labels in c-trees to inverse roles,
- ② call y an R -neighbour of x if either
 y is an R -successor of x or
 x is an R^- successor of y ,



- ③ substitute “ R -successor” in the \forall - and \exists -rule with “ R -neighbour”

still create an R -successor of x if no R -neighbour exists for $\exists R.C \in \mathcal{L}(x)$
 R^- -successor of x if no R^- -neighbour exists for an $\exists R^-.C \in \mathcal{L}(x)$

A tableau algorithm for \mathcal{ALCI} with general TBoxes

- \sqcap -rule: if $C_1 \sqcap C_2 \in \mathcal{L}(x)$, $\{C_1, C_2\} \not\subseteq \mathcal{L}(x)$, and x is not blocked
then set $\mathcal{L}(x) = \mathcal{L}(x) \cup \{C_1, C_2\}$
- \sqcup -rule: if $C_1 \sqcup C_2 \in \mathcal{L}(x)$, $\{C_1, C_2\} \cap \mathcal{L}(x) = \emptyset$, and x is not blocked
then set $\mathcal{L}(x) = \mathcal{L}(x) \cup \{C\}$ for some $C \in \{C_1, C_2\}$
- \exists -rule: if $\exists S.C \in \mathcal{L}(x)$, x has no S -neighbour y with $C \in \mathcal{L}(y)$,
and x is not blocked
then create a new node y with $\mathcal{L}(\langle x, y \rangle) = \{S\}$ and $\mathcal{L}(y) = \{C\}$
- \forall -rule: if $\forall S.C \in \mathcal{L}(x)$, there is an S -neighbour y of x with $C \notin \mathcal{L}(y)$
and x is not indirectly blocked
then set $\mathcal{L}(y) = \mathcal{L}(y) \cup \{C\}$
- \mathcal{T} -rule: if $C_1 \dot{\sqsubseteq} C_2 \in \mathcal{T}$, $\text{NNF}(\neg C_1 \sqcup C_2) \notin \mathcal{L}(x)$
and x is not blocked
then set $\mathcal{L}(x) = \mathcal{L}(x) \cup \{\text{NNF}(\neg C_1 \sqcup C_2)\}$

A tableau algorithm for \mathcal{ALCI} with general TBoxes

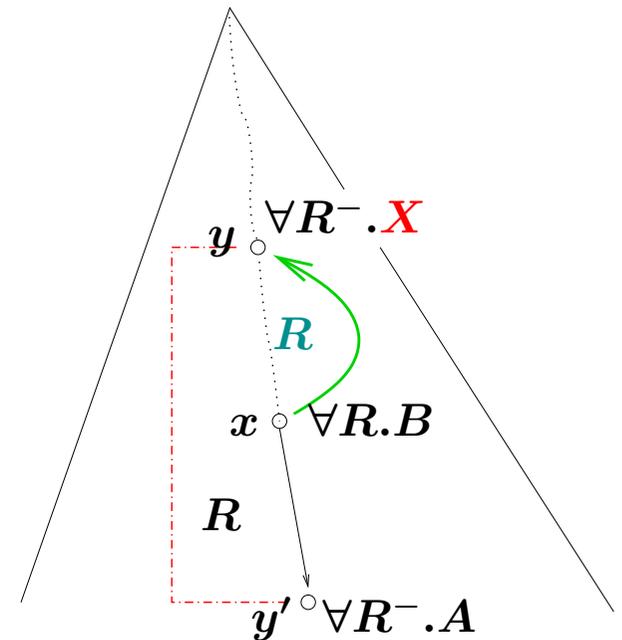
Example: is A satisfiable w.r.t. $\{A \sqsubseteq \exists R^-.A \sqcap \forall R.(\neg A \sqcup \exists S.B)\}$?

Example: is $\exists R.B$ satisfiable w.r.t. $\{B \sqsubseteq \exists R.B \sqcap \forall R^-. \forall R^-. \perp\}$?

Problem: algorithm returns “*satisfiable*” for
unsatisfiable
input \rightsquigarrow **incorrect!**

Reason: blocking condition $\mathcal{L}(y') \subseteq \mathcal{L}(y)$ is too
loose:
universal value restrictions from blocking node
may be violated

Solution: tighten blocking condition to $\mathcal{L}(y') = \mathcal{L}(y)$



④ A node x is **directly blocked** if it has an ancestor y with $\mathcal{L}(x) = \mathcal{L}(y)$.

Lemma: Let \mathcal{T} be a general \mathcal{ALCI} -Tbox and C_0 an \mathcal{ALCI} -concept. Then

1. the algorithm terminates when applied to \mathcal{T} and C_0 ,
2. the rules can be applied such that they generate a clash-free and complete completion tree iff C_0 is satisfiable w.r.t. \mathcal{T} .

Proof: (1) termination is identical to the \mathcal{ALC} case.

Proof of the Lemma: Soundness

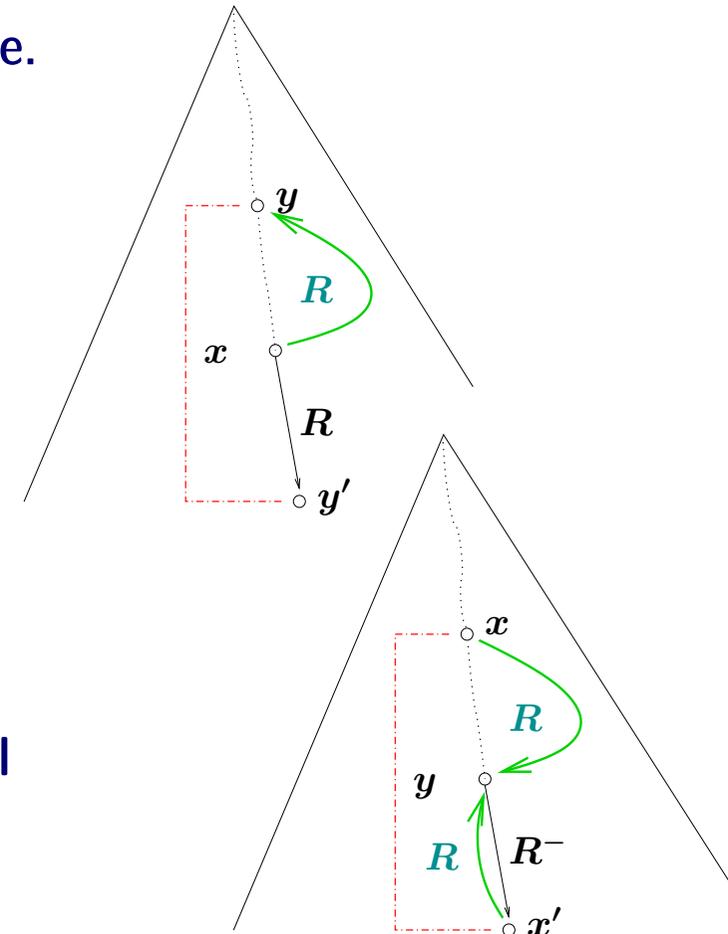
(2) let the algorithm stop with a complete and clash-free c-tree.
 Again, from this, we define an interpretation:

$$\begin{aligned} \Delta^{\mathcal{I}} &:= \{x \mid x \text{ is a node in } \mathcal{T}, x \text{ is not blocked}\} \\ A^{\mathcal{I}} &:= \{x \in \Delta^{\mathcal{I}} \mid A \in \mathcal{L}(x)\} \text{ for concept names } A \\ R^{\mathcal{I}} &:= \{\langle x, y \rangle \in \Delta^{\mathcal{I}^2} \mid y \text{ is an } R\text{-succ of } x \text{ or} \\ &\quad y \text{ blocks an } R\text{-succ of } x \text{ or} \\ &\quad x \text{ is an } R^-\text{-succ of } y \text{ or} \\ &\quad x \text{ blocks an } R^-\text{-succ of } y \} \end{aligned}$$

and show, by induction on the structure of concepts, for all $x \in \Delta^{\mathcal{I}}$, $D \in \text{sub}(C_0, \mathcal{T})$:

$$D \in \mathcal{L}(x) \text{ implies } x \in D^{\mathcal{I}}.$$

As for \mathcal{ALC} , this implies that \mathcal{I} is indeed a model of C_0 and \mathcal{T}



(3) completely identical to the *ALC* case...

That's it!

I hope you got an idea of how we can

- build tableau algorithms for description logics and
- see that they do indeed what we want them to do, i.e., decide satisfiability

Research Challenges

Challenges

➔ Increased expressive power

- Existing DL systems implement (at most) *SHIQ*
- OWL extends *SHIQ* with datatypes and nominals

➔ Scalability

- Very large KBs
- Reasoning with (very large numbers of) individuals

➔ Other reasoning tasks

- Querying
- Matching
- Least common subsumer
- ...

➔ Tools and Infrastructure

- Support for large scale ontological engineering and deployment

Increased Expressive Power: Datatypes

- ➡ **OWL** has simple form of datatypes
 - Unary predicates plus disjoint object-class/datatype domains
- ➡ Well understood **theoretically**
 - Existing work on **concrete domains** [Baader & Hanschke, Lutz]
 - Algorithm already known for *SHOQ(D)* [Horrocks & Sattler]
 - Can use **hybrid reasoning** (DL reasoner + datatype “oracle”)
- ➡ May be **practically** challenging
 - All XMLS datatypes supported (?)
- ➡ Already seeing some (partial) **implementations**
 - Cerebra system (Network Inference), Racer system (Hamburg)

Increased Expressive Power: Nominals

- ➡ OWL **oneOf** constructor equivalent to hybrid logic **nominals**
 - Extensionally defined concepts, e.g., $EU \equiv \{\text{France, Italy, \dots}\}$
- ➡ Theoretically **very challenging**
 - Resulting logic has known **high complexity** (NExpTime)
 - No known “practical” algorithm
 - Not obvious how to extend tableaux techniques in this direction
 - Loss of tree model property
 - Spy-points: $\top \sqsubseteq \exists R.\{Spy\}$
 - Finite domains: $\{Spy\} \sqsubseteq \leq nR^-$
- ➡ **Standard solution** is weaker semantics for nominals
 - Treat nominals as (disjoint) primitive classes
 - Loss of completeness/soundness

Increased Expressive Power: Extensions

- ➡ OWL **not expressive enough** for all applications
- ➡ Extensions **wish list** includes:
 - Feature chain (path) agreement, e.g., output of component of composite process equals input of subsequent process
 - Complex roles/role inclusions, e.g., a city located in part of a country is located in that country
 - Rules—proposal(s) already exist for “datalog/LP style rules”
 - Temporal and spatial reasoning
 - ...
- ➡ May be impossible/undesirable to resist such extensions
- ➡ Extended language sure to be **undecidable**
- ➡ How can extensions best be **integrated** with OWL?
- ➡ How can reasoners be developed/adapted for extended languages
 - Some existing work on language **fusions** and **hybrid** reasoners

Scalability

- ➔ Reasoning **hard** (ExpTime) even without nominals (i.e., \mathcal{SHIQ})
- ➔ Web ontologies may grow **very large**
- ➔ Good **empirical evidence** of scalability/tractability for DL systems
 - E.g., 5,000 (complex) classes; 100,000+ (simple) classes
- ➔ But evidence mostly w.r.t. \mathcal{SHF} (no inverse)
- ➔ **Problems** can arise when \mathcal{SHF} extended to \mathcal{SHIQ}
 - Important **optimisations** no longer (fully) work
- ➔ Reasoning with **individuals**
 - **Deployment** of web ontologies will mean reasoning with (possibly very large numbers of) individuals/tuples
 - Unlikely that standard **Abox** techniques will be able to cope

Performance Solutions (Maybe)

☞ Excessive **memory usage**

- Problem exacerbated by over-cautious double blocking condition (e.g., root node can never block)
- Promising results from more precise blocking condition [Sattler & Horrocks]

☞ **Qualified number restrictions**

- Problem exacerbated by naive expansion rules
- Promising results from optimised expansion using Algebraic Methods [Haarslev & Möller]

☞ **Caching** and merging

- Can still work in some situations (work in progress)

☞ Reasoning with **very large KBs**

- DL systems shown to work with $\approx 100k$ concept KB [Haarslev & Möller]
- But KB only exploited small part of DL language

Other Reasoning Tasks

Querying

- Retrieval and instantiation wont be sufficient
- Minimum requirement will be **DB style query language**
- May also need “what can I say about x ?” style of query

Explanation

- To support ontology design
- Justifications and proofs (e.g., of query results)

“**Non-Standard Inferences**”, e.g., LCS, matching

- To support ontology integration
- To support “bottom up” design of ontologies

Summary

- ➔ **Description Logics** are family of logical KR formalisms
- ➔ **Applications** of DLs include DataBases and **Semantic Web**
 - Ontologies will provide vocabulary for semantic markup
 - OWL web ontology language based on *SHIQ* DL
 - Set to become W3C standard (OWL) & already widely adopted
 - Use of DL provides formal foundations and reasoning support
- ➔ **DL Reasoning** based on tableau algorithms
- ➔ **Highly Optimised** implementations used in DL systems
- ➔ **Challenges** remain
 - Reasoning with full OWL language
 - (Convincing) demonstration(s) of scalability
 - New reasoning tasks
 - Development of (high quality) tools and infrastructure

Resources

Slides from this talk

<http://www.cs.man.ac.uk/~horrocks/Slides/Innsbruck-tutorial/>

FaCT system (open source)

<http://www.cs.man.ac.uk/FaCT/>

OilEd (open source)

<http://oiled.man.ac.uk/>

OIL

<http://www.ontoknowledge.org/oil/>

W3C Web-Ontology (WebOnt) working group (OWL)

<http://www.w3.org/2001/sw/WebOnt/>

DL Handbook, Cambridge University Press

<http://books.cambridge.org/0521781760.htm>

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